

Sistem Komunikasi 1

Bab 2

Transformasi Fourier

Analog Vs. Digital (1)

Advantages of Digital Communication

As the signals are digitized, there are many advantages of digital communication over analog communication, such as:

- The effect of distortion, noise, and interference is much less in digital signals as they are less affected.
- Digital circuits are more reliable.
- Digital circuits are easy to design and cheaper than analog circuits.
- The hardware implementation in digital circuits, is more flexible than analog.

Analog Vs. Digital (2)

- The occurrence of cross-talk is very rare in digital communication.
- The signal is un-altered as the pulse needs a high disturbance to alter its properties, which is very difficult.
- Signal processing functions such as encryption and compression are employed in digital circuits to maintain the secrecy of the information.
- The probability of error occurrence is reduced by employing error detecting and error correcting codes.
- Spread spectrum technique is used to avoid signal jamming.

Analog Vs. Digital (3)

- Combining digital signals using Time Division Multiplexing (TDM) is easier than combining analog signals using Frequency Division Multiplexing (FDM).
- The configuring process of digital signals is easier than analog signals.
- Digital signals can be saved and retrieved more conveniently than analog signals.
- Many of the digital circuits have almost common encoding techniques and hence similar devices can be used for a number of purposes.
- The capacity of the channel is effectively utilized by digital signals.

Formula Transformasi Fourier

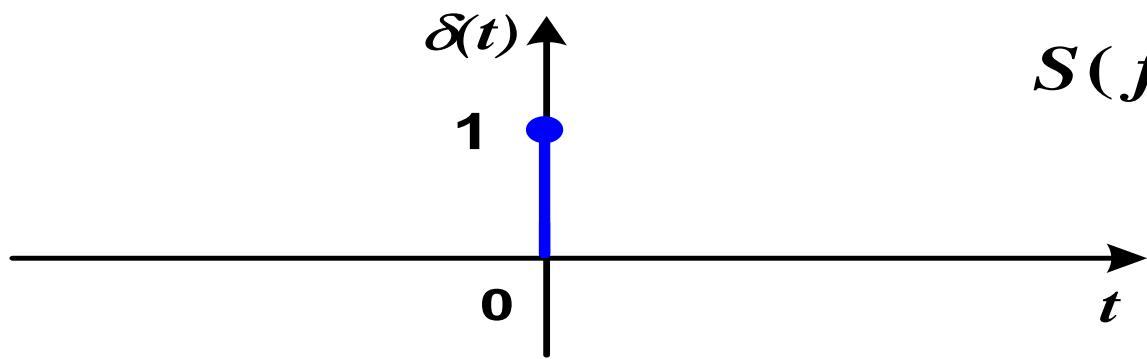
$$S(f) = \int_{-\infty}^{+\infty} s(t) \cdot e^{-j2\pi ft} dt$$

- $S(f)$ dinamakan Transformasi Fourier dari $s(t)$
- Jika Transformasi Fourier $S(f)$ suatu sinyal diketahui maka kita dapat menghitung persamaan sinyal dalam domain waktu $s(t)$ dengan formula Inverse Transformasi Fourier

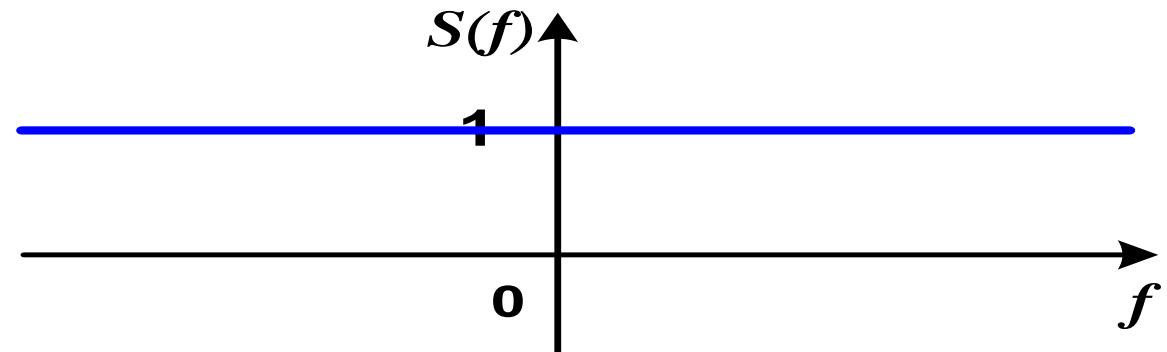
$$s(t) = \int_{-\infty}^{+\infty} S(f) \cdot e^{j2\pi ft} df$$

Beberapa Transformasi penting

- Transformasi Fourier impulse (sinyal delta dirac):

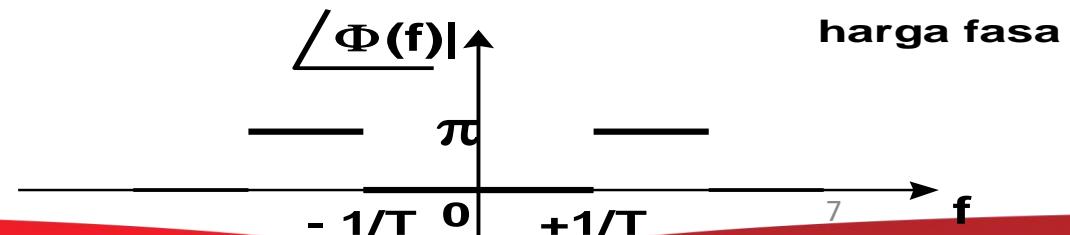
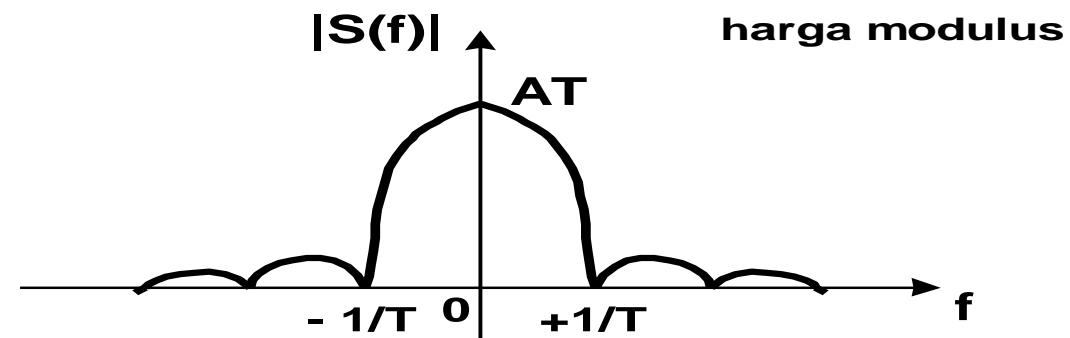
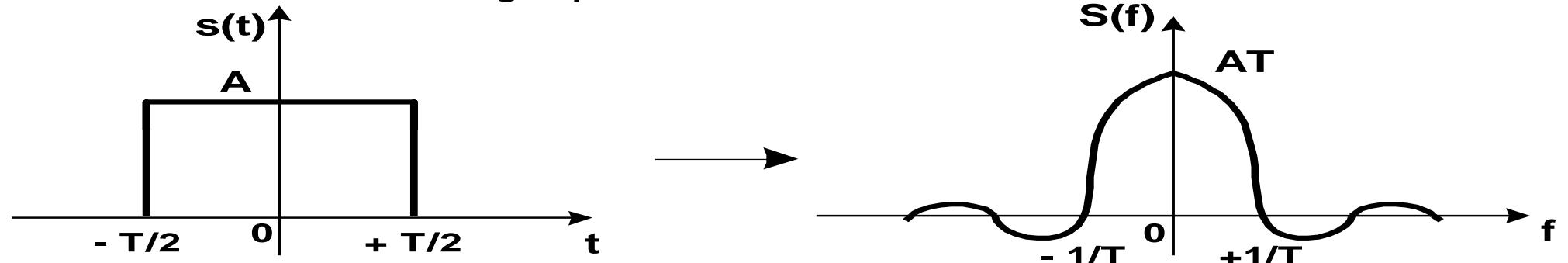


$$S(f) = \int_{-\infty}^{+\infty} \delta(t) \cdot e^{-j2\pi ft} dt = 1$$



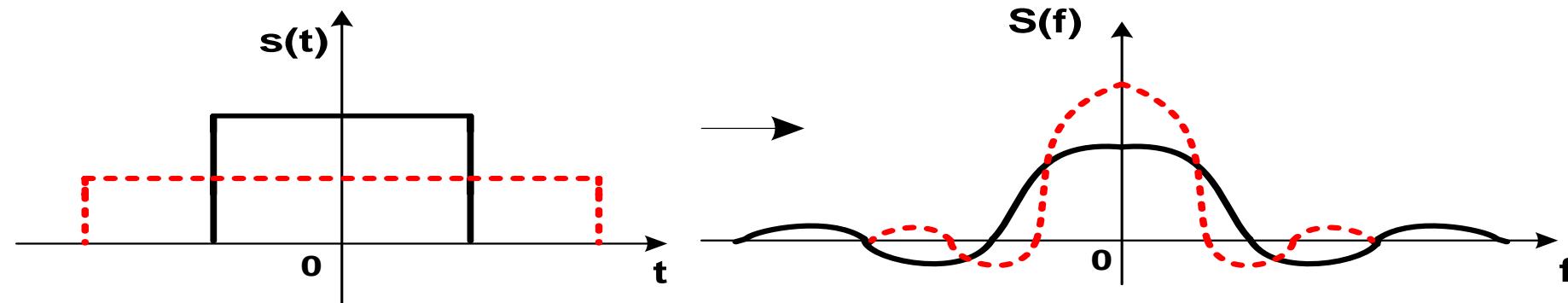
Beberapa Transformasi penting

- Transformasi Fourier dari fungsi pulsa:



Sifat-sifat Transformasi Fourier (yang sering dipakai di siskom)

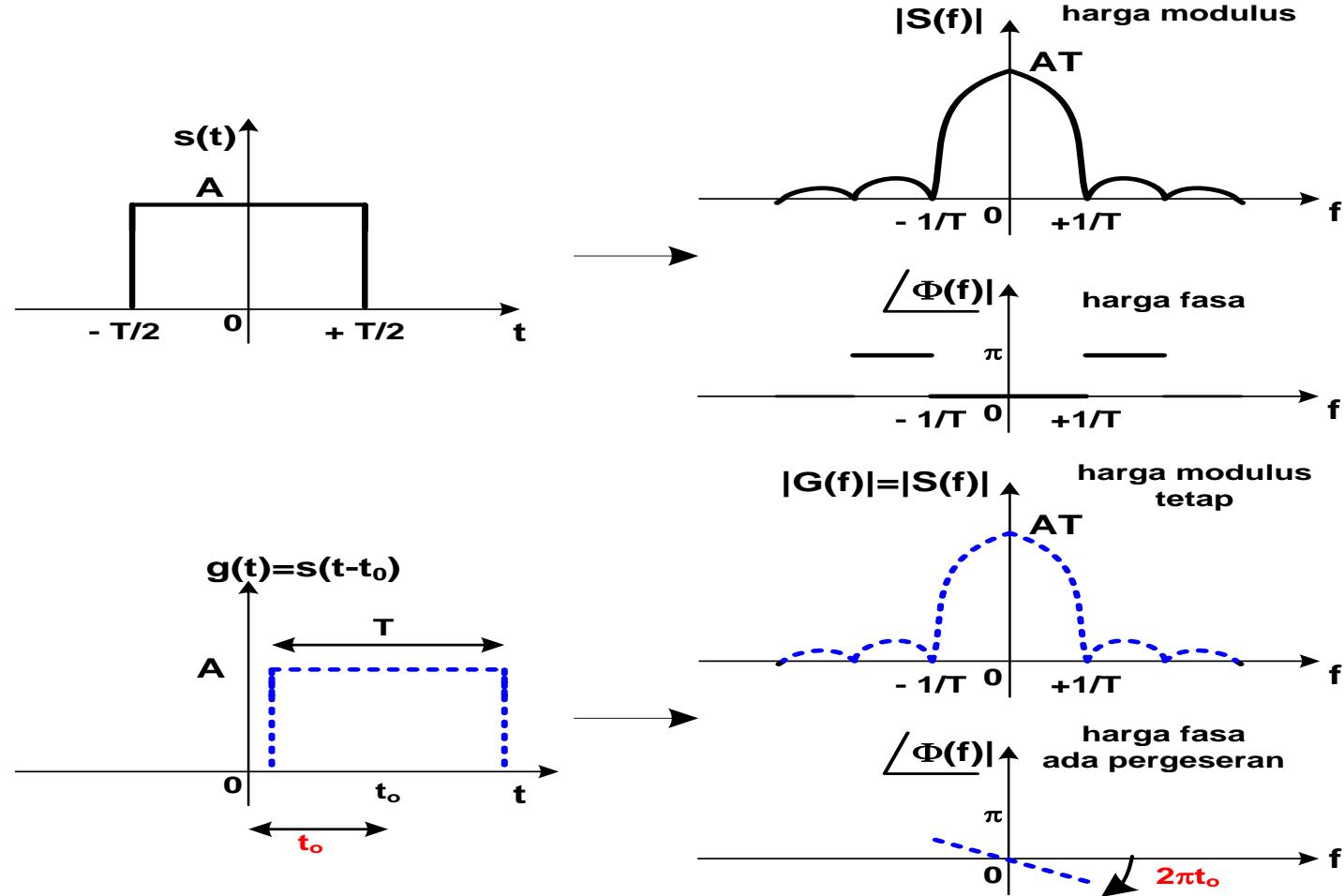
a. Time Scaling



Sifat-sifat Transformasi Fourier

b. Time shifting

Bila $s(t) \leftrightarrow S(f)$ maka $s(t-t_0) \leftrightarrow S(f)e^{-j2\pi f t_0}$

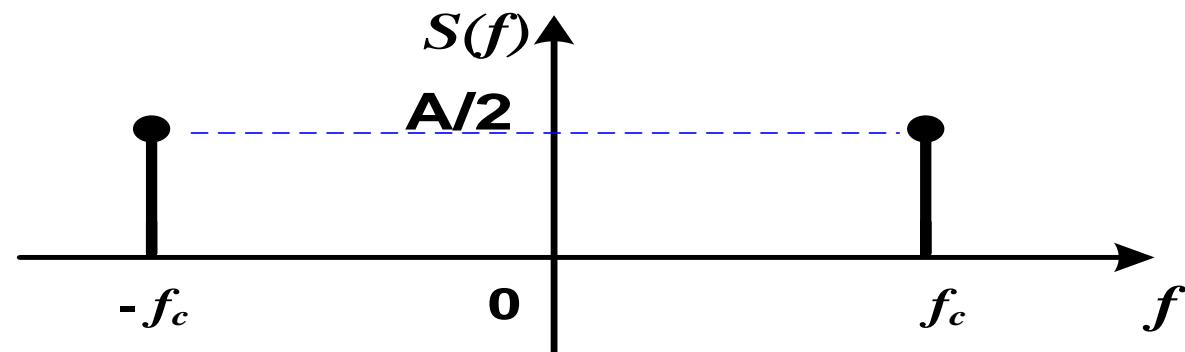


Sifat-sifat Transformasi Fourier

c. Frequency shifting

Bila $s(t) \leftrightarrow S(f)$ maka $S(f-f_o) \leftrightarrow s(t) \cdot e^{-j2\pi f_o t}$

- Contoh : $s(t) = A \cos 2\pi f_c t = \frac{A}{2} (e^{j2\pi f_c t} + e^{-j2\pi f_c t})$
- maka $S(f) = \frac{A}{2} \delta(f + f_c) + \frac{A}{2} \delta(f - f_c)$



Sifat-sifat Transformasi Fourier

d. Transformasi Fourier Sinyal Periodik

Bila $x(t) \leftrightarrow X(f)$ (untuk sinyal tidak periodik)

Maka untuk

$$x_p(t) = \sum_{n=-\infty}^{+\infty} x(t - nT_0)$$

($\rightarrow x(t)$ periodik dengan periode T_0)

Transformasi fourier dari $x_p(t)$

$$X_p(f) = \frac{1}{T_0} \sum_{m=-\infty}^{+\infty} X\left(\frac{m \cdot f}{T_0}\right) \cdot \delta\left(f - \frac{m}{T_0}\right)$$

Sifat-sifat Transformasi Fourier

e. Integrasi pada kawasan waktu:

Bila $s(t) \leftrightarrow S(f)$, kemudian menghasilkan $S(0)=0$,
maka :

$$\int_{-\infty}^t s(t) \cdot dt \Leftrightarrow \frac{1}{j2\pi f} \cdot S(f)$$

f. Diferensiasi pada kawasan waktu:

Bila $s(t) \leftrightarrow S(f)$, jika pada kawasan waktu dilakukan
diferensiasi sekali, **maka :**

$$\frac{d}{dt} s(t) \Leftrightarrow j2\pi f \cdot S(f)$$

Sifat-sifat Transformasi Fourier

g. Konvolusi pada kawasan waktu:

Bila $s_1(t) \leftrightarrow S_1(f)$ dan $s_2(t) \leftrightarrow S_2(f)$,

maka :

$$\int_{-\infty}^{\infty} s_1(\tau).s_2(t - \tau)d\tau \Leftrightarrow S_1(f).S_2(f)$$

h. Perkalian pada kawasan waktu:

Bila $s_1(t) \leftrightarrow S_1(f)$ dan $s_2(t) \leftrightarrow S_2(f)$,

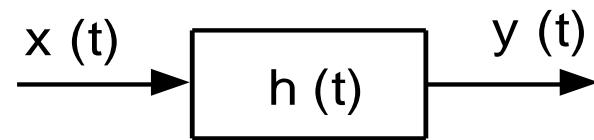
maka :

$$s_1(t).s_2(t) \Leftrightarrow \int_{-\infty}^{\infty} S_1(\lambda).S_2(f - \lambda)d\lambda$$

Transmisi Sinyal melalui Sistem Linier

Respon Time :

Time Domain



$h(t) \equiv$ respon impuls

$$y(t) = h(\lambda) \int_{-\infty}^{\infty} x(t-\lambda) d\lambda$$

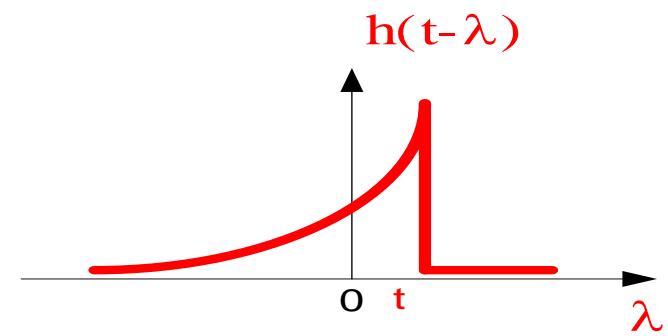
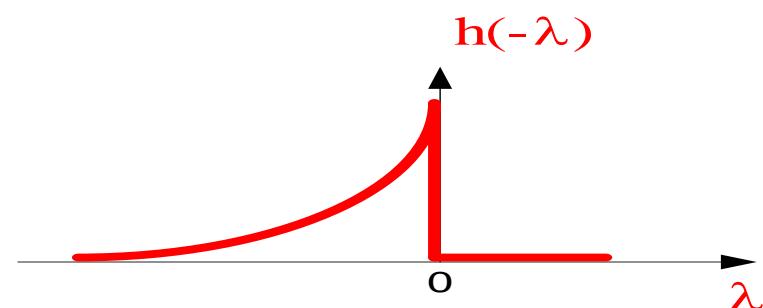
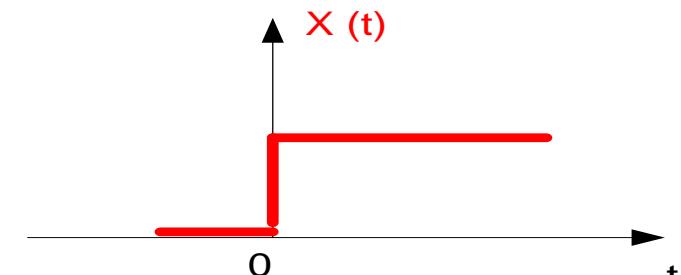
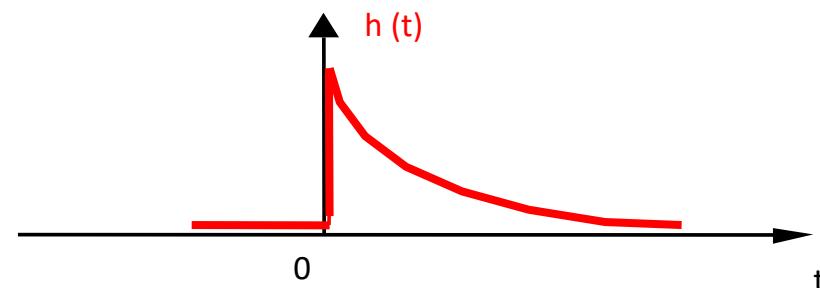
$$= x(\lambda) \int_{-\infty}^{\infty} h(t-\lambda) d\lambda$$

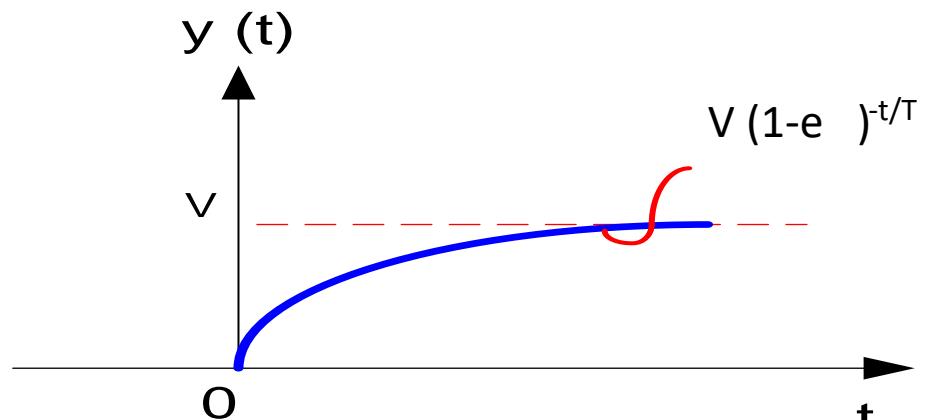
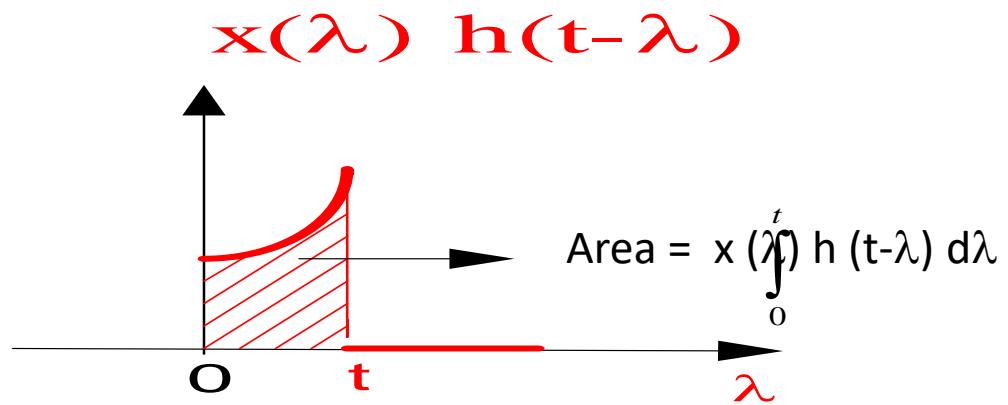
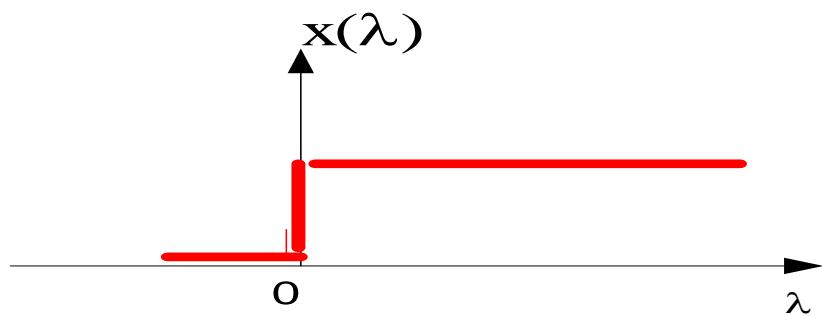
$$= x(t) \otimes h(t)$$

$$= h(t) \otimes x(t)$$

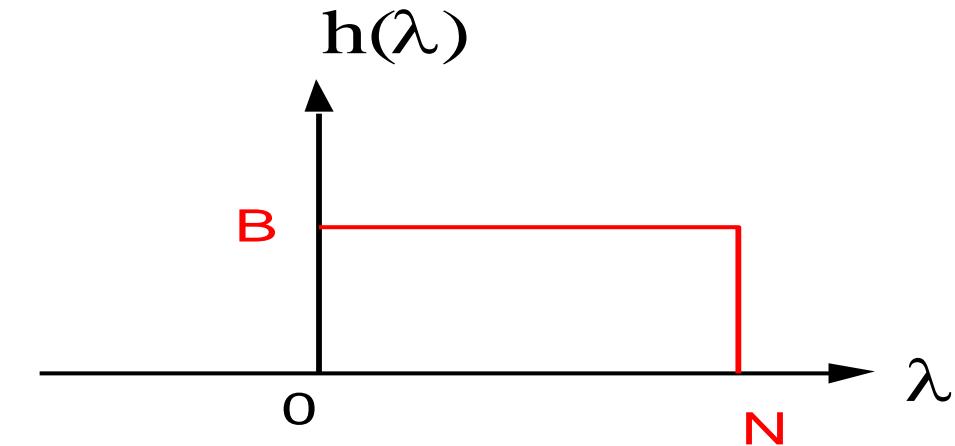
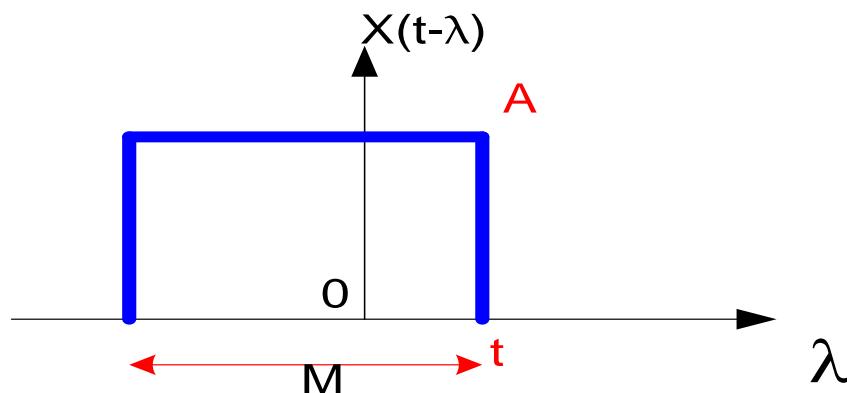
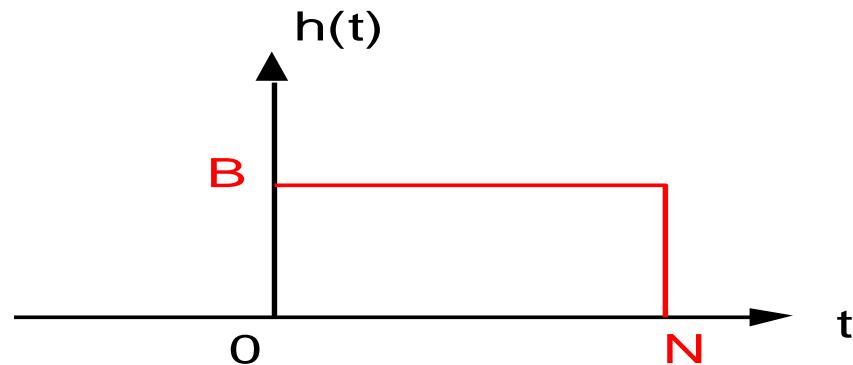
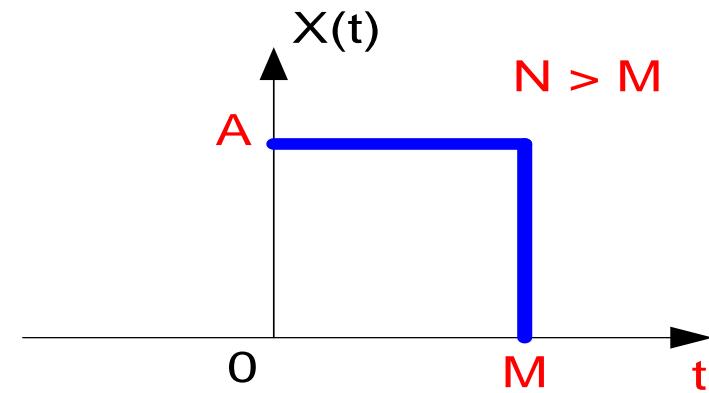
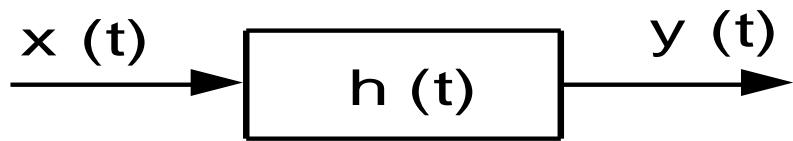
Perhitungan Konvolusi :

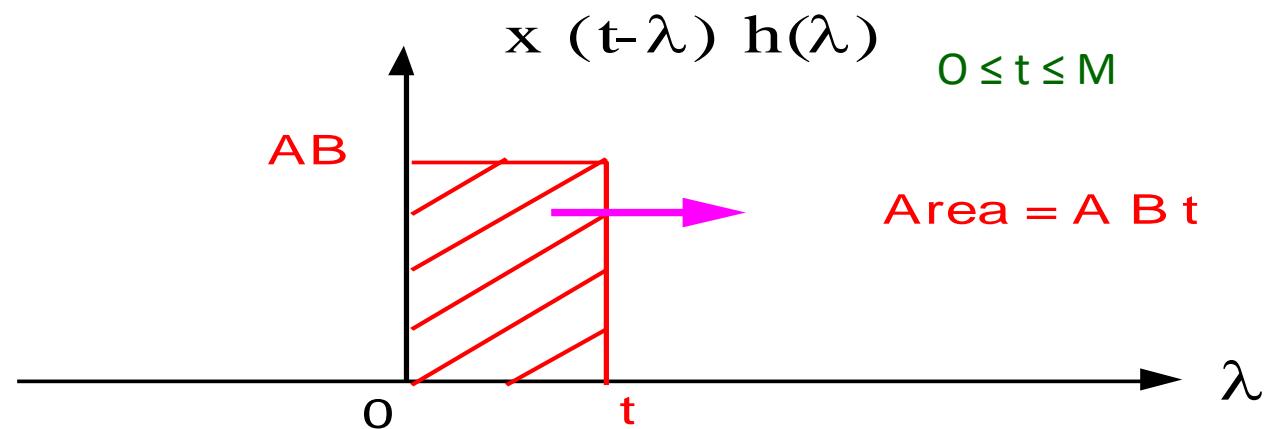
Representasi Grafis ; contoh





Contoh Perhitungan Konvolusi dgn representasi Grafis :



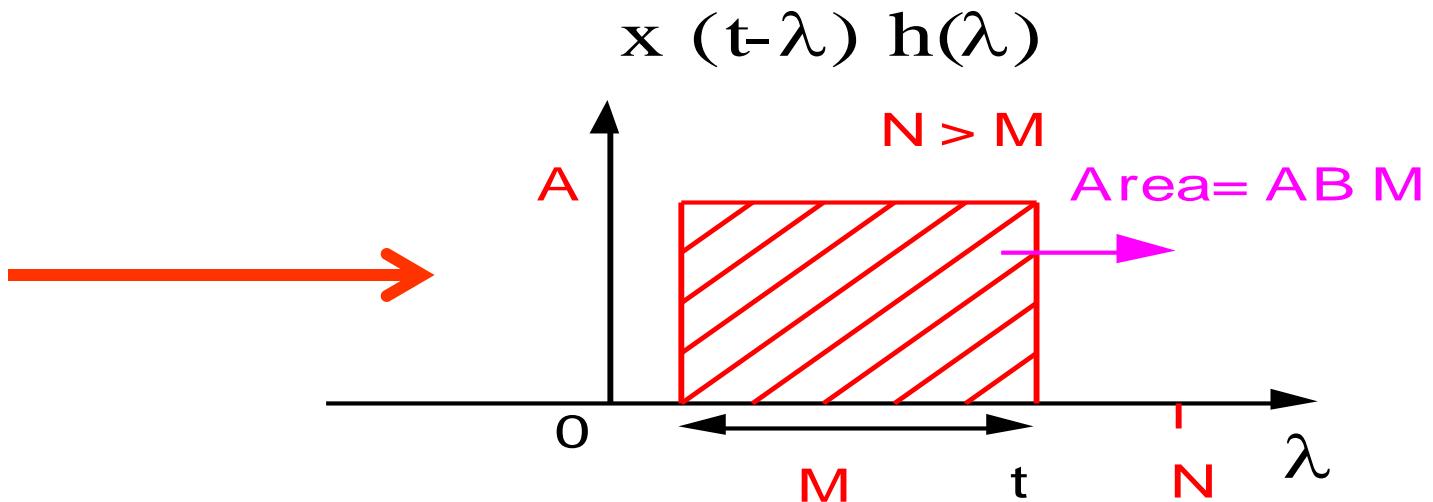


Perhitungan

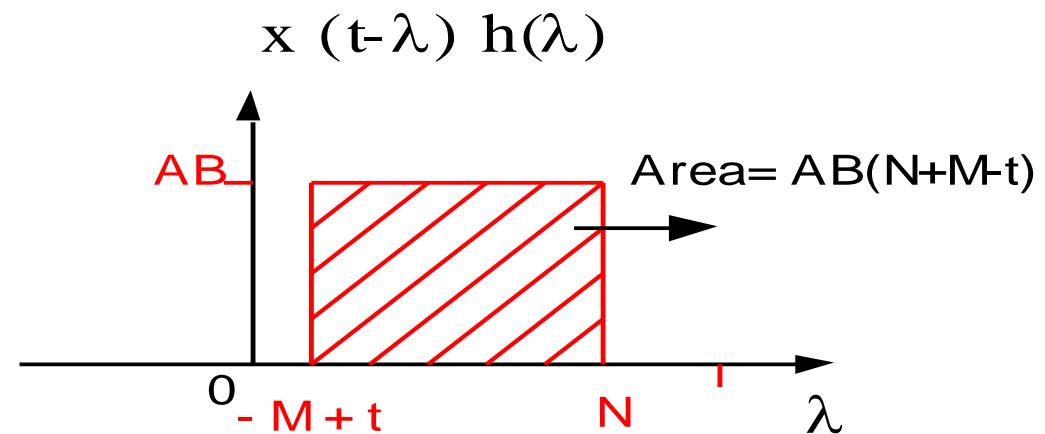
Karena $N > M$:

untuk $0 \leq t \leq M$: $y(t) = ABt$

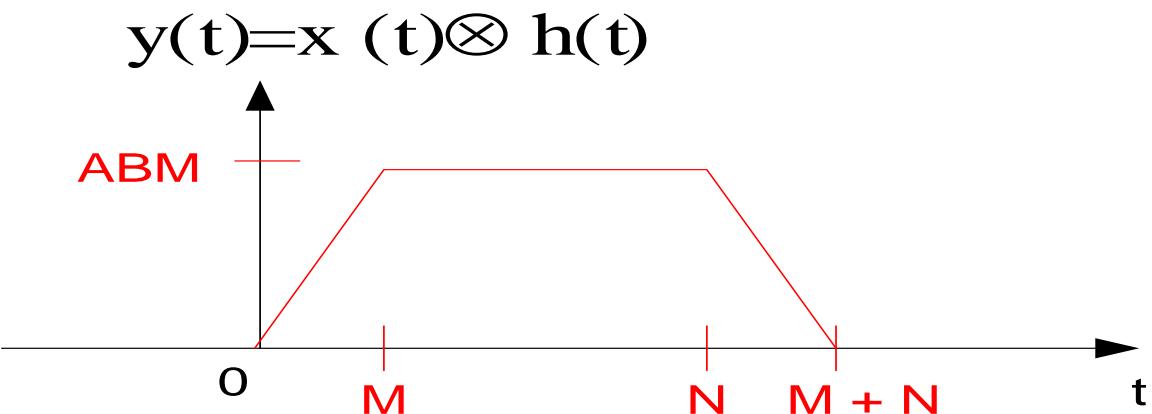
untuk $M \leq t \leq N$:



untuk $t \geq N$:



Sehingga:

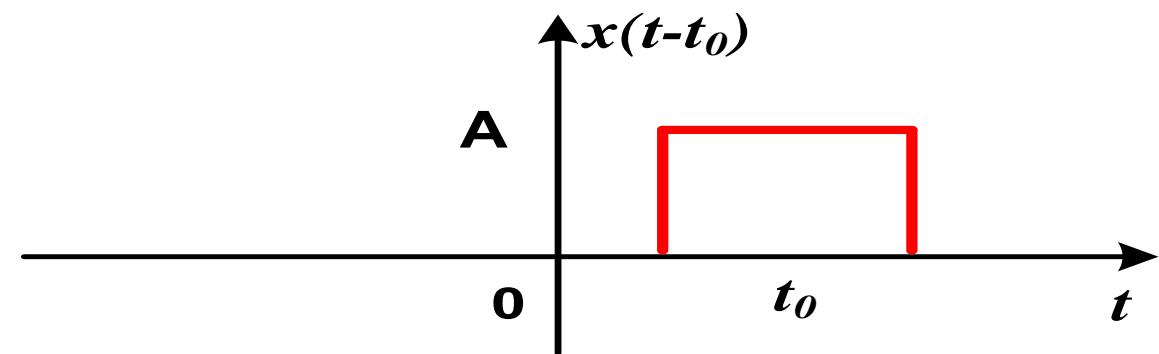
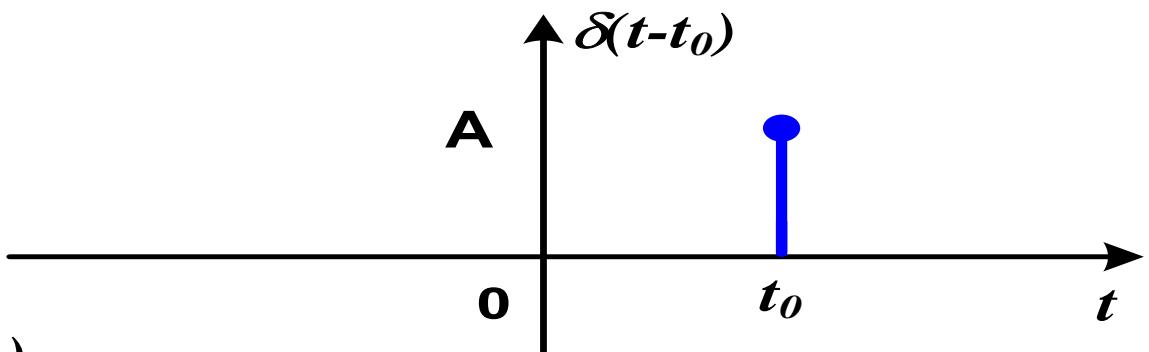
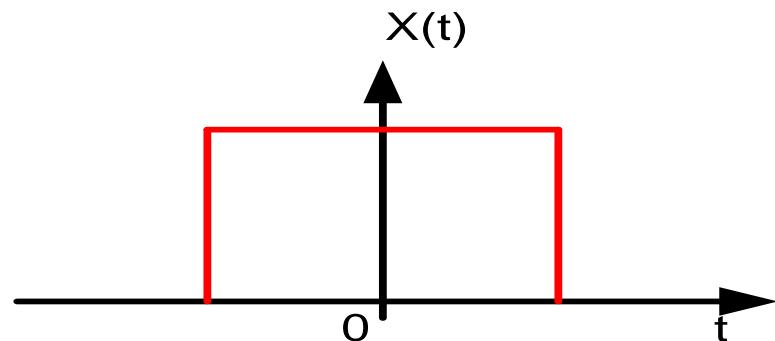


Kasus Khusus :

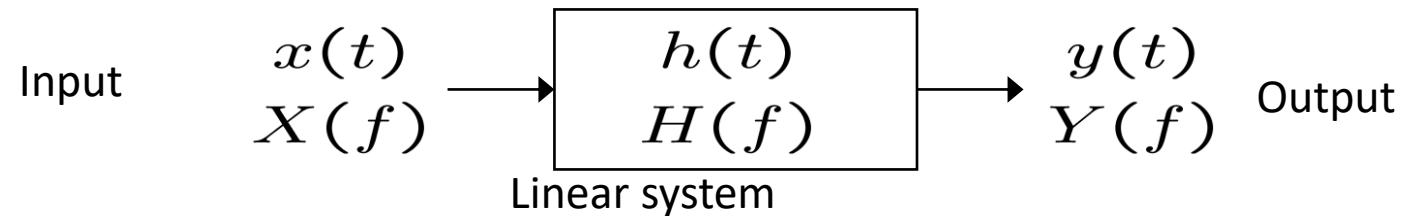
Konvolusi dengan fungsi $\delta(t - t_0)$

- $x(t) \otimes \delta(t - t_0) = x(t - \lambda) \int_{-\infty}^{\infty} (\lambda - t_0) d\lambda = x(t - t_0)$

- $x(t) \otimes A \delta(t - t_0) = A x(t - t_0)$



Transmisi Sinyal Melalui Sistem Linier



- Deterministic signals:

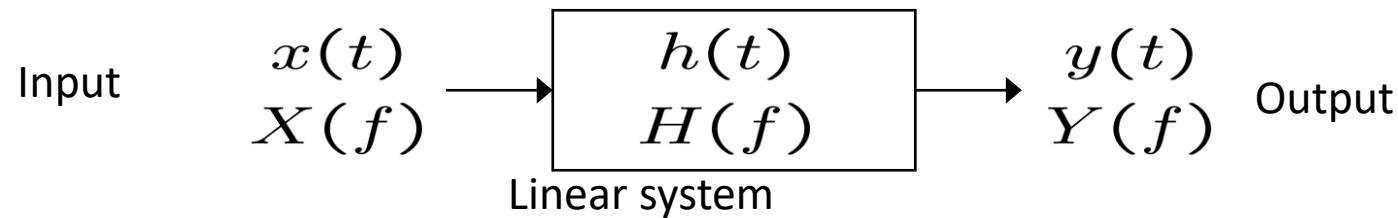
$$Y(f) = X(f)H(f)$$

- Random signals:

$$G_Y(f) = G_X(f)|H(f)|^2$$

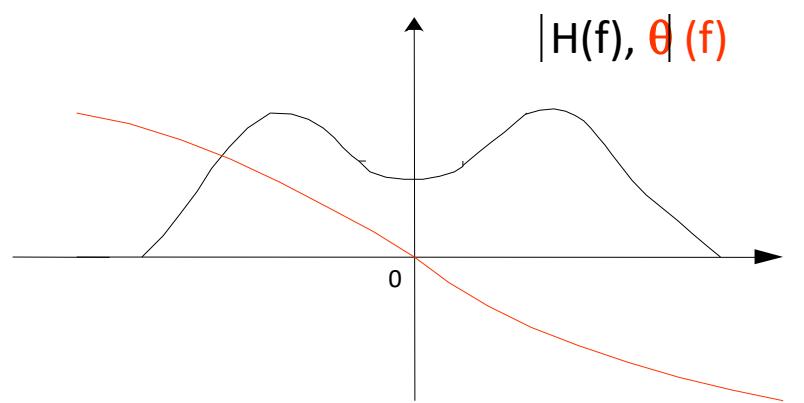
- $Y(f)$ = Sinyal output dalam domain frekuensi
- $X(f)$ = Sinyal input dalam domain frekuensi
- $H(f)$ = Respons frekuensi sistem linier
- $G_Y(f)$ = PSD (Power Spectral Density) sinyal output
- $G_X(f)$ = PSD (Power Spectral Density) sinyal input

Sistem Lowpass vs Bandpass

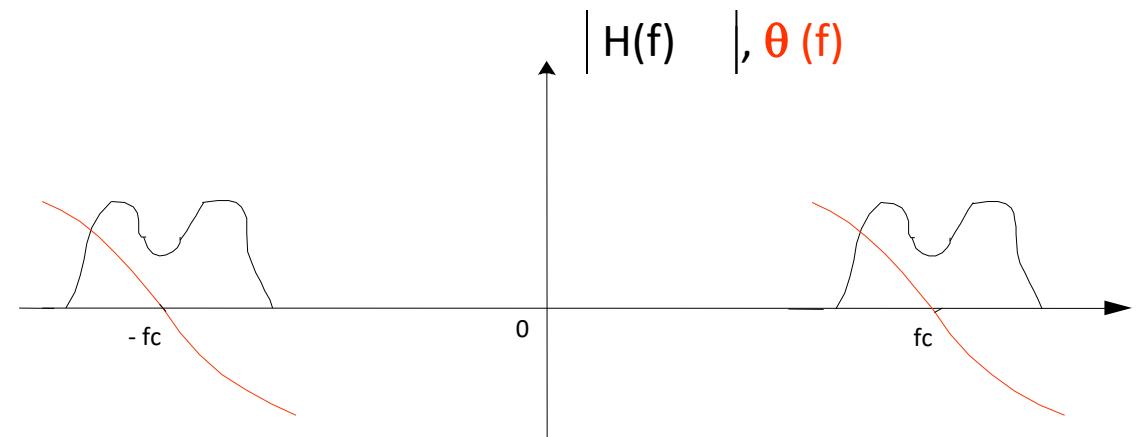


Jika $h(t)$ riil $\Rightarrow H(f)$ kompleks $\rightarrow |H(f)|$ merupakan fungsi genap
 $\rightarrow \theta(f)$ merupakan fungsi ganjil

Sistem “lowpass”



Sistem “bandpass”

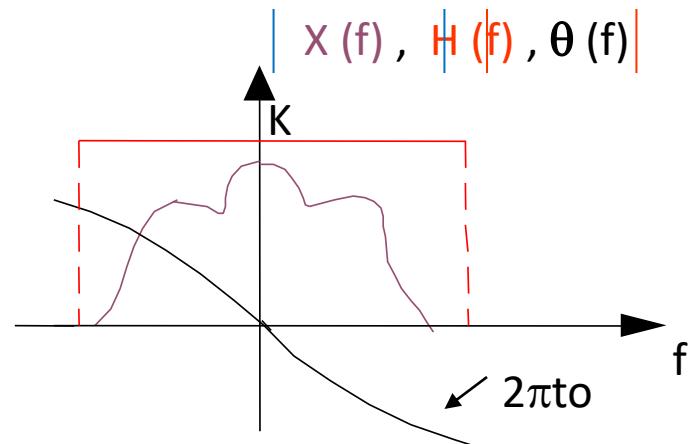


- Kondisi “distortionless transmission”

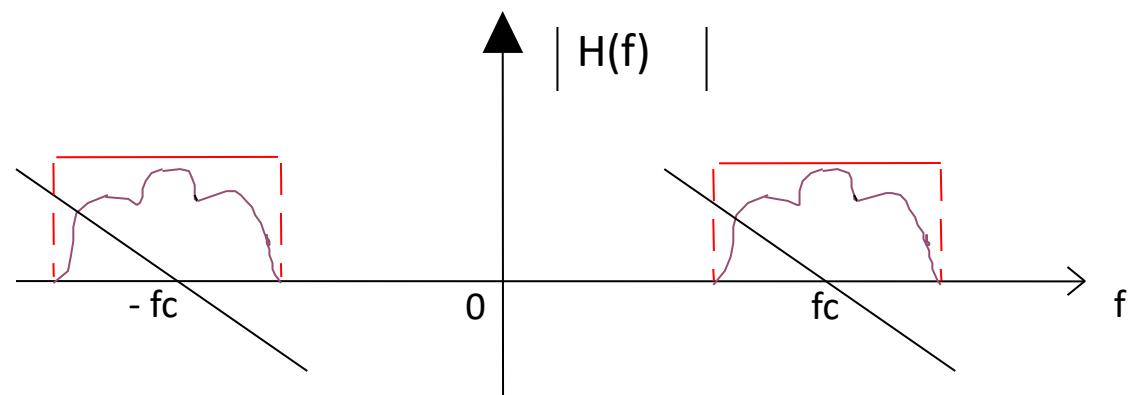


$$y(t) = K \cdot X(t - t_0)$$

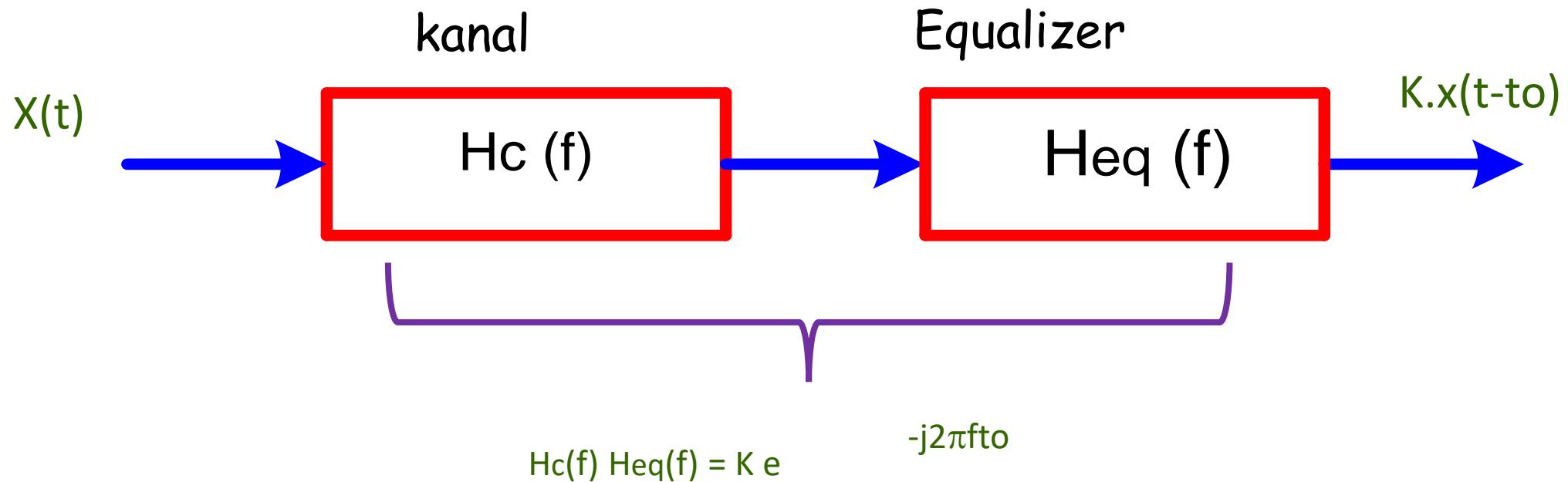
$$H(f) = K e^{-j2\pi f t_0}$$



- Untuk sistem “bandpass”



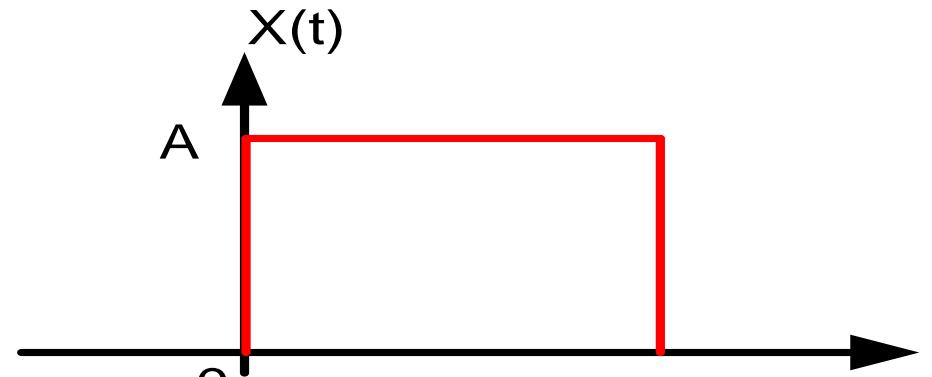
- Distorsi Linier dan Prinsip Ekualisasi Kanal



$$H_{eq}(f) = K e^{\frac{-j2\pi f t_0}{H_c(f)}}$$

Latihan Soal

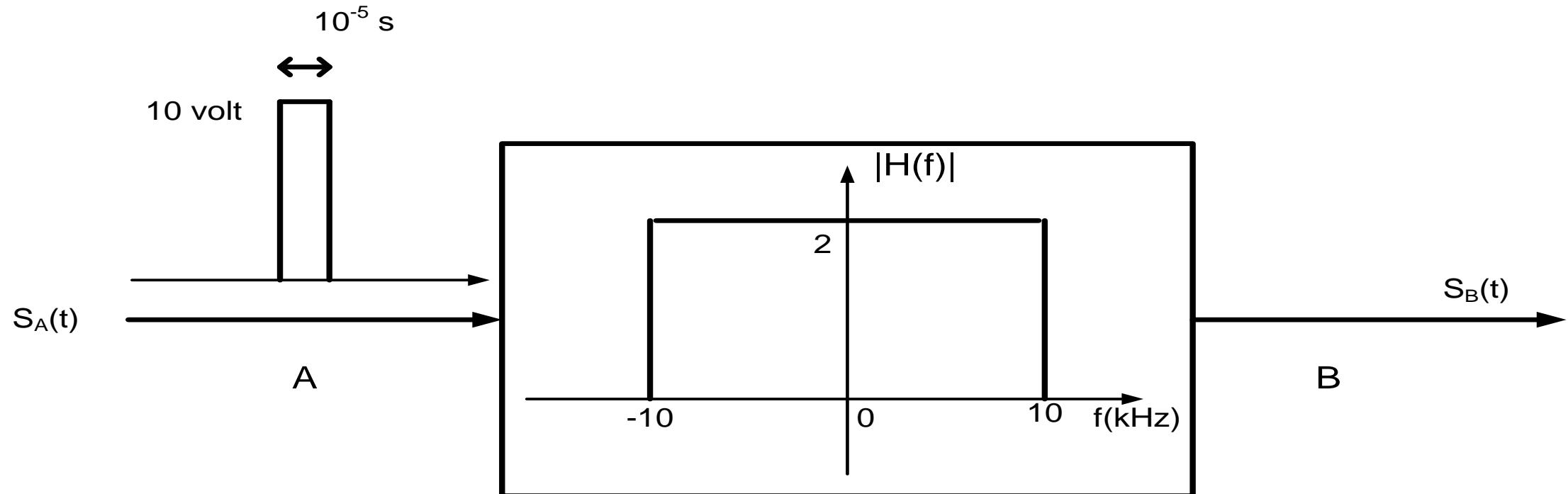
1. Perhatian gambar sinyal $x(t)$ diawah ini :



- Tentukan $X(f)^0$ yang merupakan transformasi fourier dari sinyal tersebut !
- Jika sinyal $z(t) = x(t) \cdot y(t)$ dimana $y(t) = \cos(4\pi t/T)$, tentukan $Z(f)$!
- Gambarkan $z(t)$ dan $Z(f)$

Latihan Soal

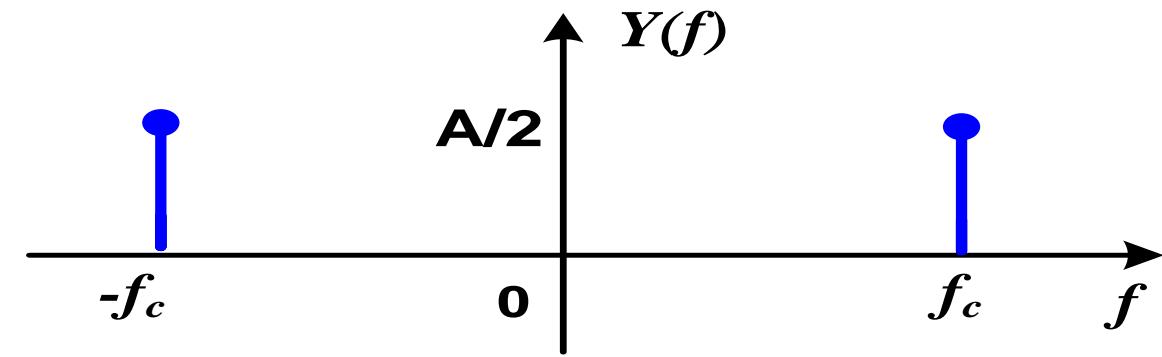
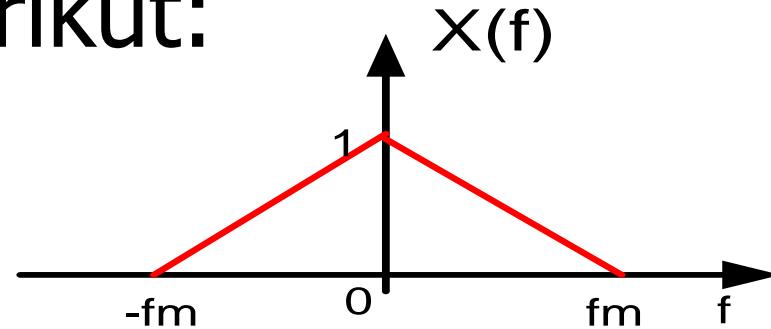
2. Suatu sinyal memasuki sistem yang diwakili oleh LPF berikut ini :



Tentukan $S_A(f)$, $S_B(f)$, $S_B(t)$!

Latihan Soal

3. Diketahui sinyal dalam domain frekuensi sebagai berikut:



- a. Untuk $f_c > fm$, Gambarkan $Z(f) = X(f)*Y(f)$!
- b. Tentukan persamaan $z(t)$, gambar diagram proses yang terjadi !