

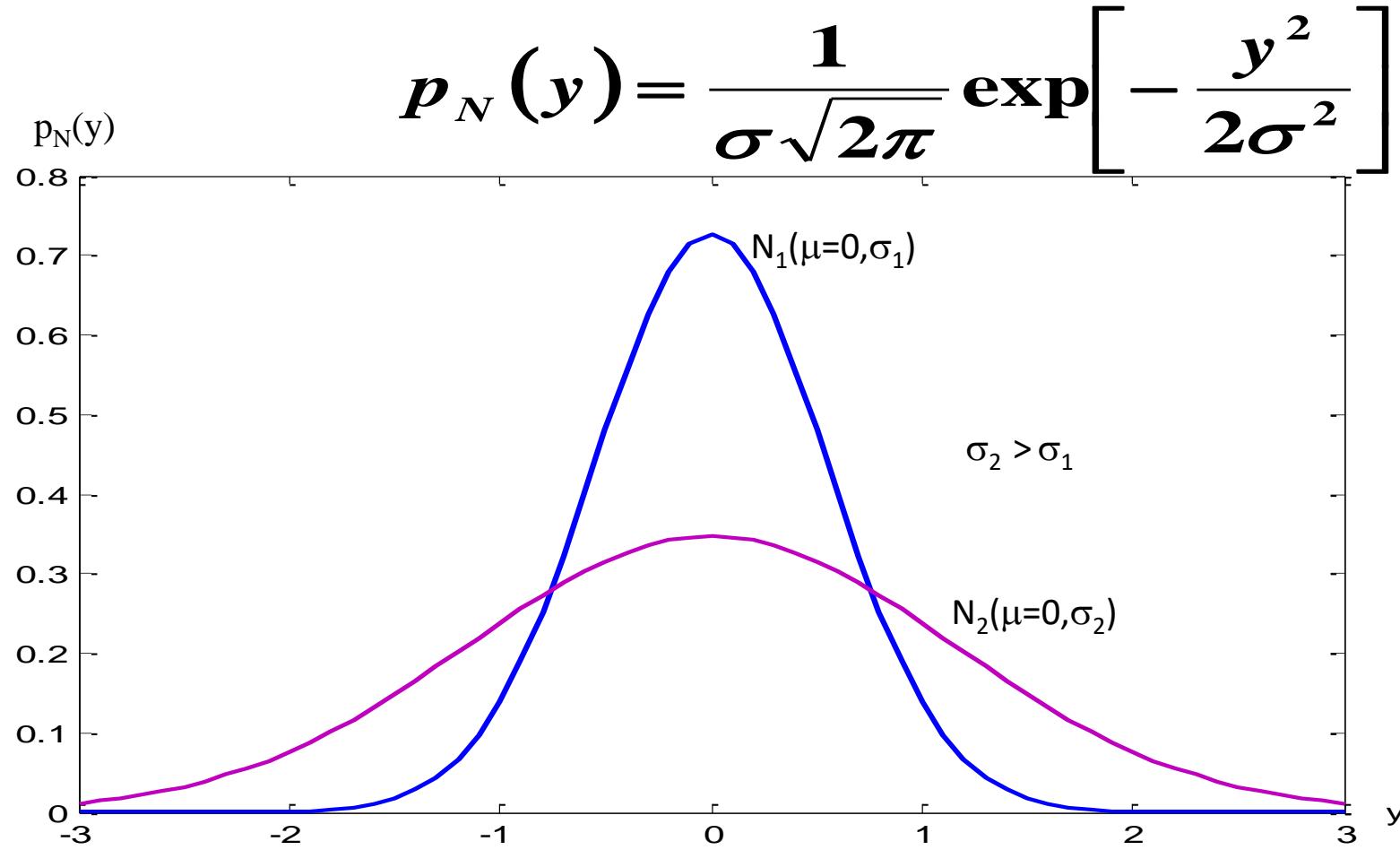
Sistem Komunikasi 1

Bab 10

Probabilitas Error

Gaussian/Normal

- **Normal Distribution:** Completely characterized by mean (μ) and variance (σ^2)



Gaussian: Rapidly Dropping Tail Probability!

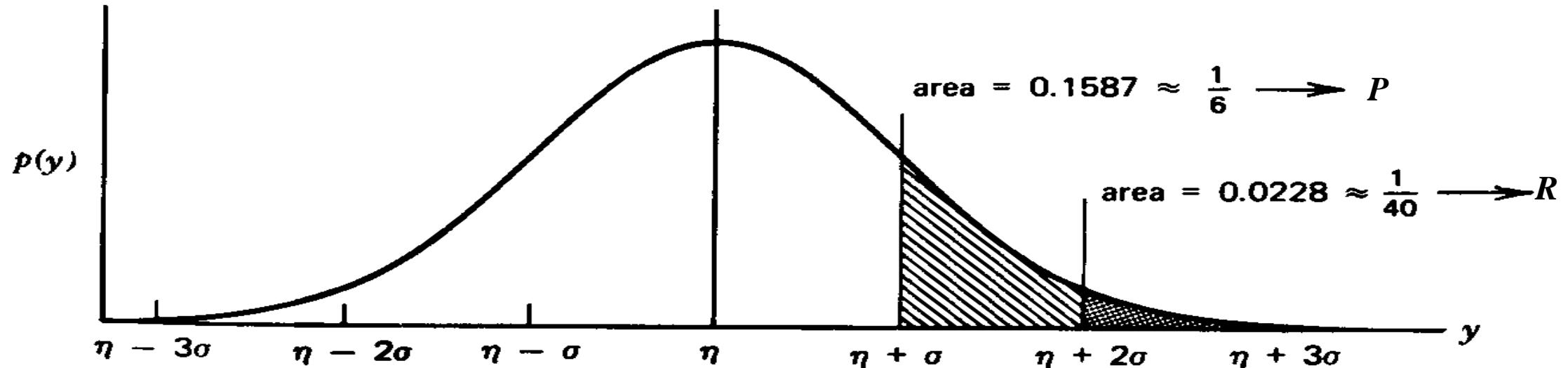


FIGURE 2.12. Tail areas of the normal distribution.

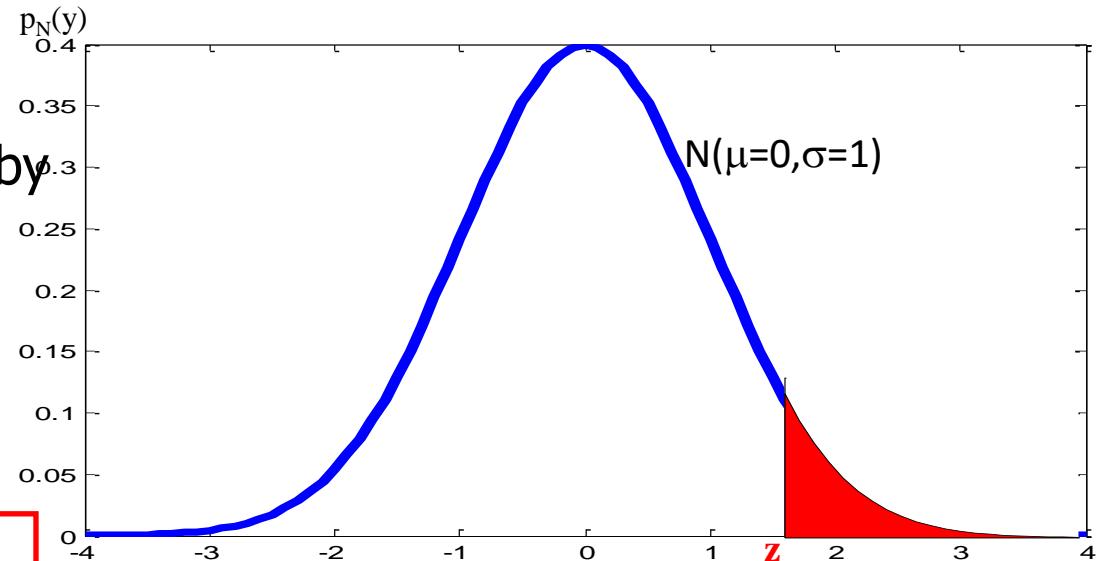
$$P = \frac{1}{\sigma\sqrt{2\pi}} \int_{\eta+\sigma}^{\infty} \exp\left[-\frac{(y-\eta)^2}{2\sigma^2}\right] dy$$

$$R = \frac{1}{\sigma\sqrt{2\pi}} \int_{\eta+2\sigma}^{\infty} \exp\left[-\frac{(y-\eta)^2}{2\sigma^2}\right] dy$$

Review Probabilitas dan Statistik

Gaussian/Normal

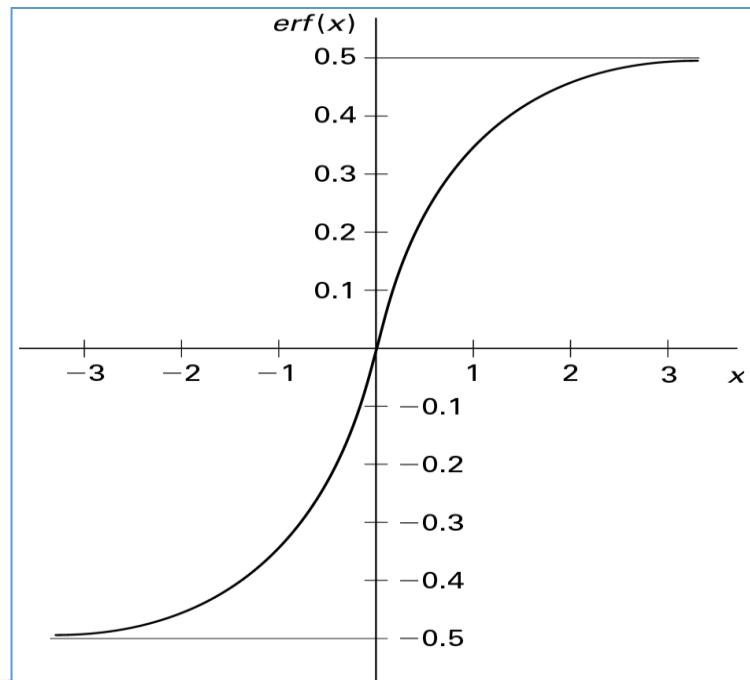
- **Normal Distribution:** Completely characterized by mean ($\mu=0$) and variance ($\sigma^2=1$)
- **Q-function:** one-sided tail of normal pdf



$$Q(z) \triangleq p(y > z) = \int_z^\infty \frac{1}{\sqrt{2\pi}} e^{-y^2/2} dy.$$

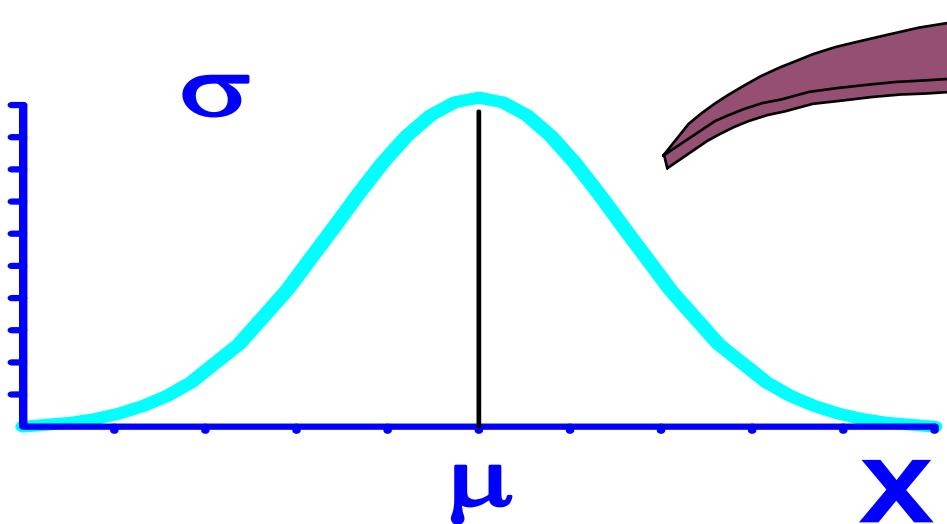
- **erfc():** two-sided tail.
- So:

$$Q(z) = \frac{1}{2} \operatorname{erfc}\left(\frac{z}{\sqrt{2}}\right).$$



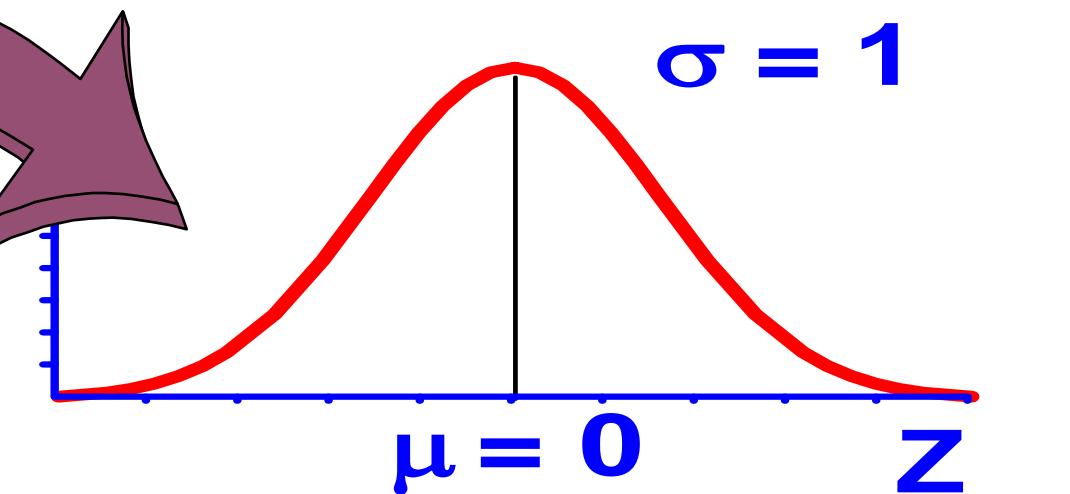
Standardize the Normal Distribution

Normal
Distribution



$$z = \frac{x - \mu}{\sigma}$$

Standardized Normal Distribution



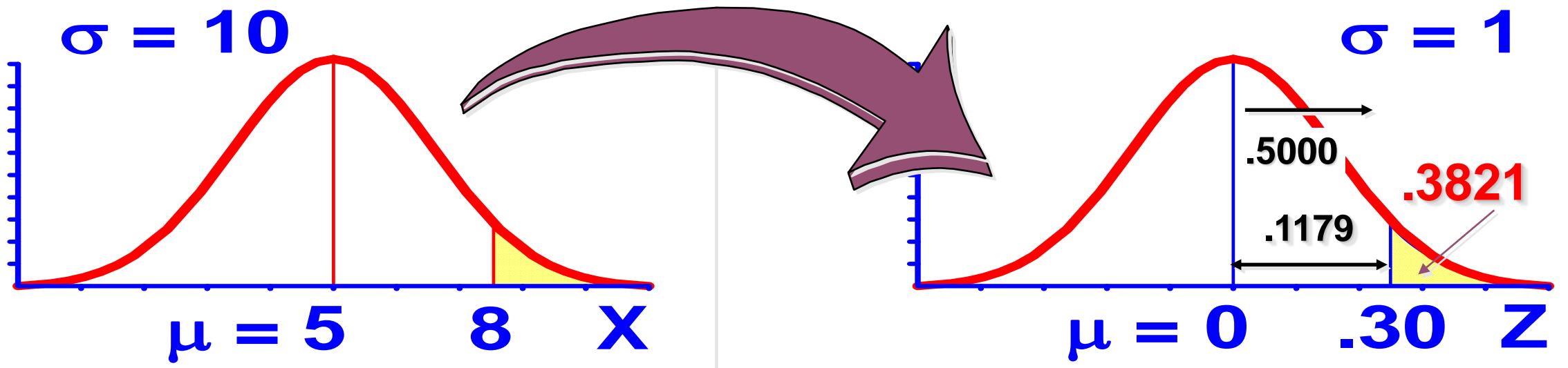
One table!

Example $P(X \geq 8)$

Normal
Distribution

$$Z = \frac{X - \mu}{\sigma} = \frac{8 - 5}{10} = .30$$

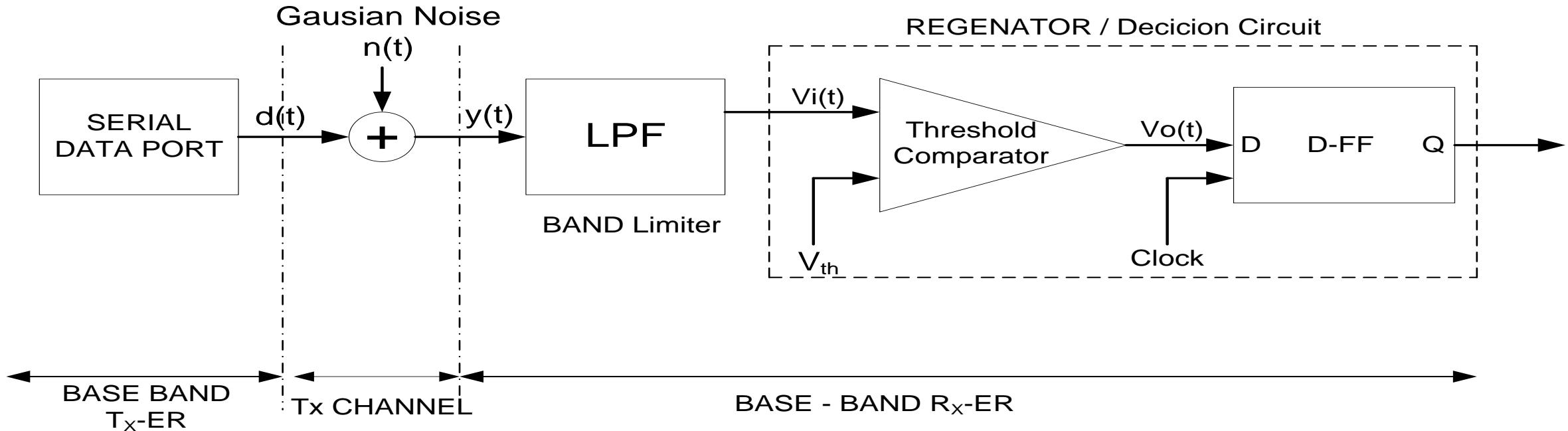
Standardized Normal Distribution



Shaded area exaggerated

PERTANYAAN ! Luas daerah yang diarsir = $0.3821 = Q(??); ?? = 0.3$

Baseband Digital Transmission Link



Sinyal Terima + AWGN

original message
 $d(t)$

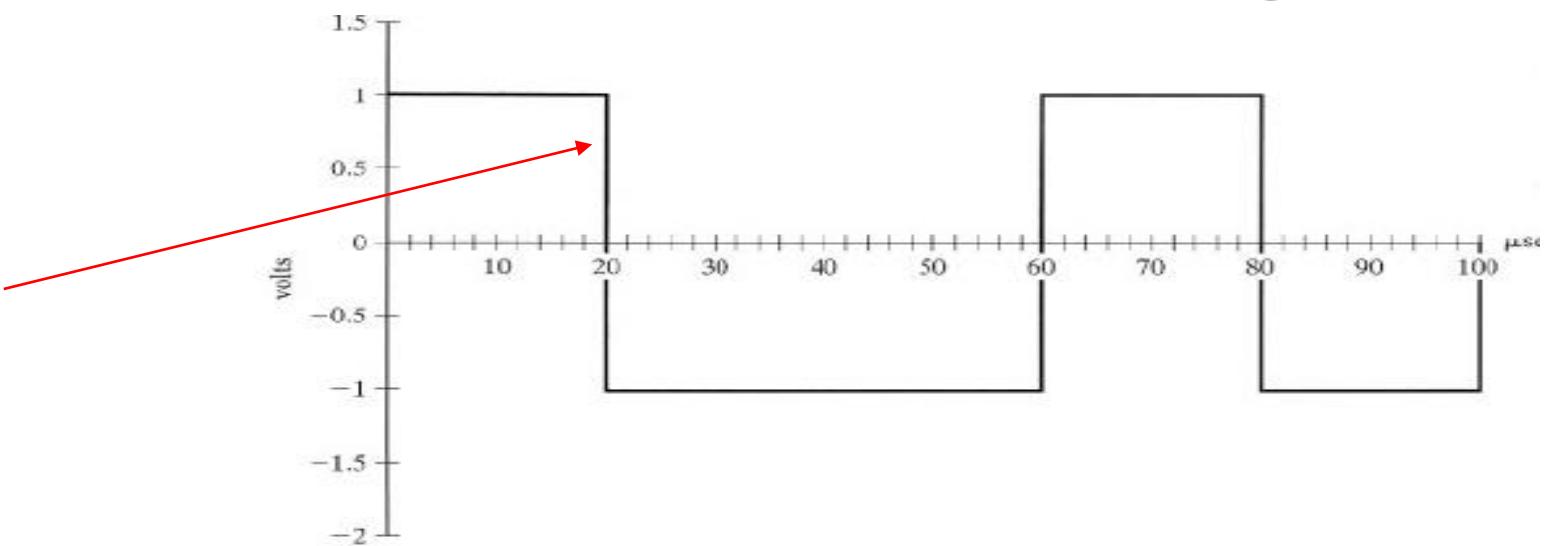
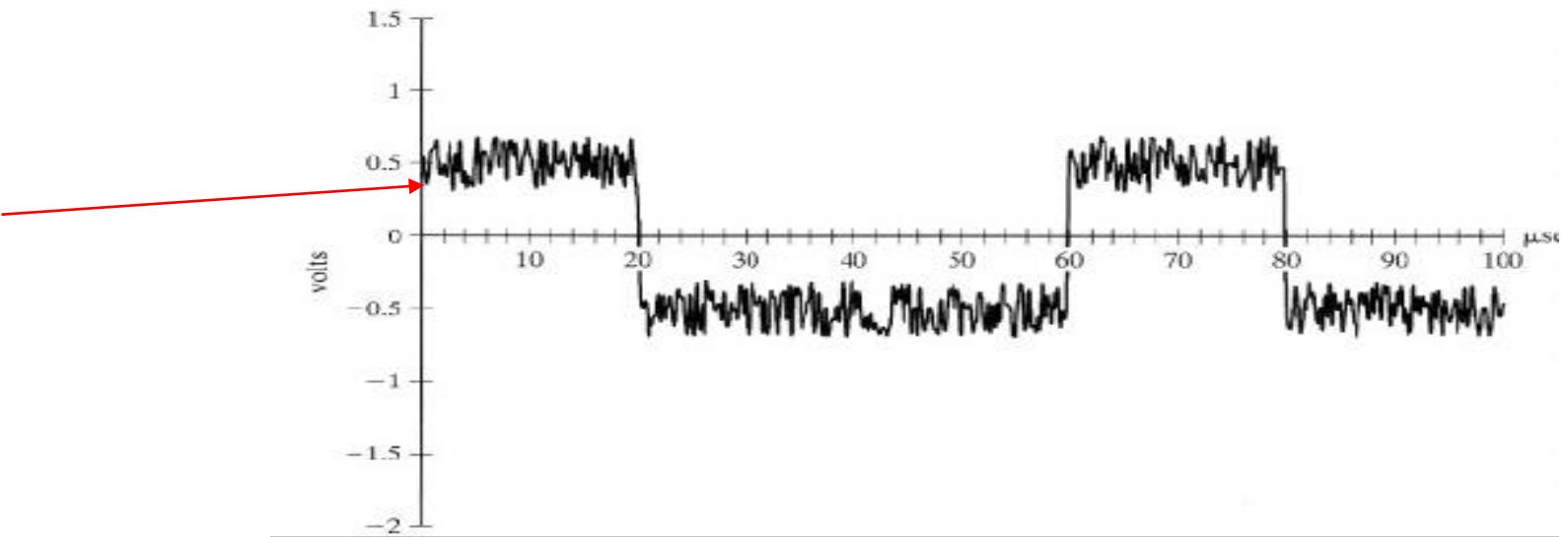


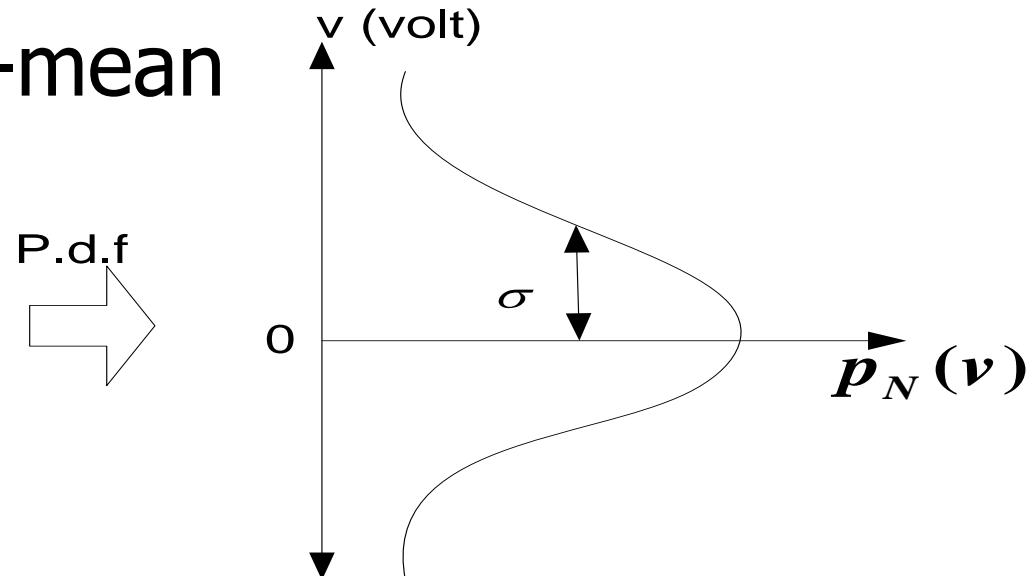
Figure 3-23a Transmitted signal for "10010" using rectangular pulses.

received wave
 $y(t)=d(t)+n(t)$



AWGN

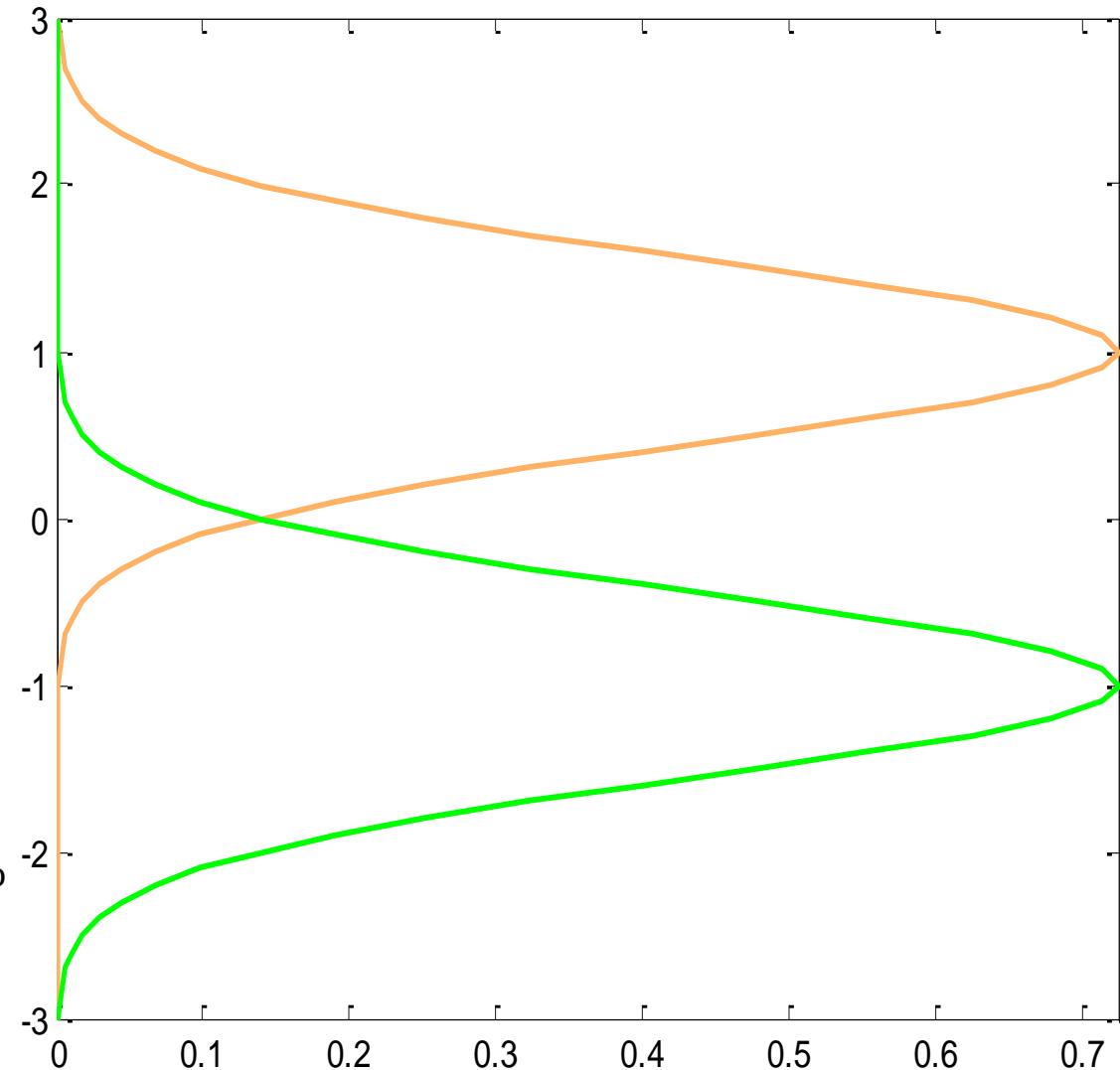
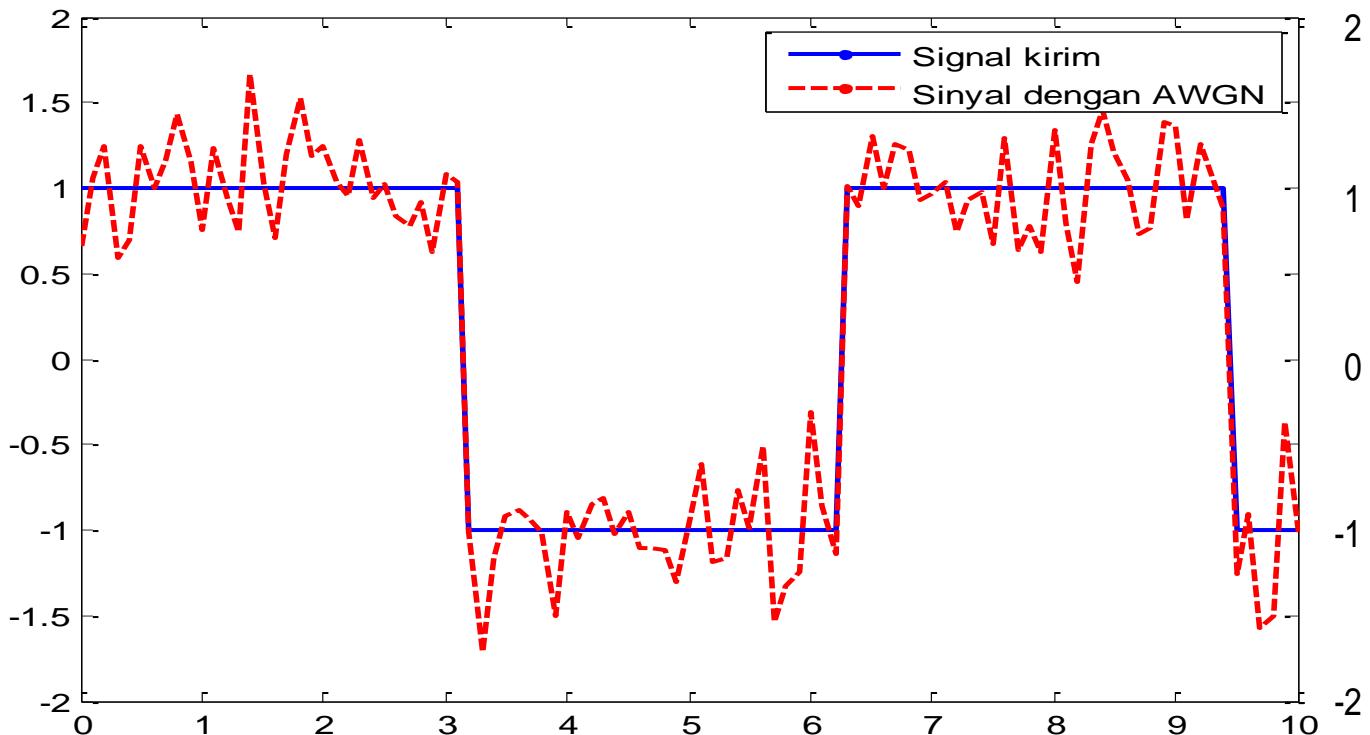
- $n(t)$ ~~adalah~~ gaussian noise dengan zero-mean

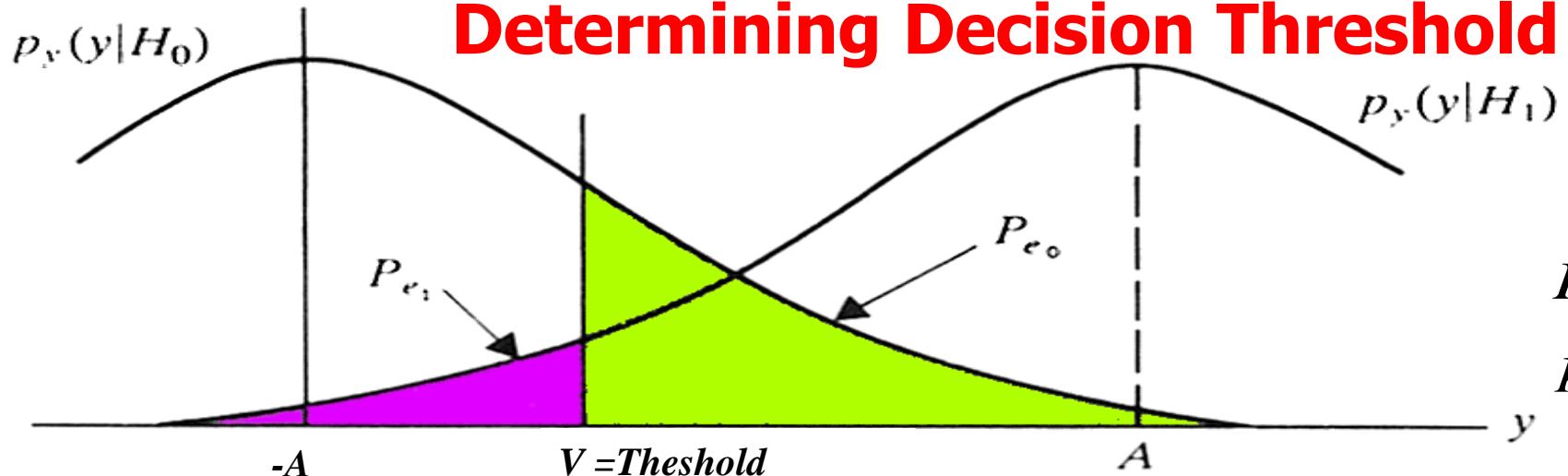


$$p_N(v) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{v^2}{2\sigma^2}\right]$$

- σ = standar deviasi = tegangan effektive noise

Gangguan Noise Terhadap Sinyal Digital





The comparator implements decision rule:

$$P_{e_1} \equiv P(Y < V | H_1) = \int_{-\infty}^V p_Y(y | H_1) dy$$

$$P_{e_0} \equiv P(Y > V | H_0) = \int_V^{\infty} p_Y(y | H_0) dy$$

Average error error probability:

$$P_e = P_0 P_{e_0} + P_1 P_{e_1}$$

$$P_0 = P_1 = 1/2 \Rightarrow P_e = \frac{1}{2}(P_{e_0} + P_{e_1})$$

Choose H_0 ($a_k=0$) if $Y < V$
 Choose H_1 ($a_k=1$) if $Y > V$

Channel noise is Gaussian with the pdf:

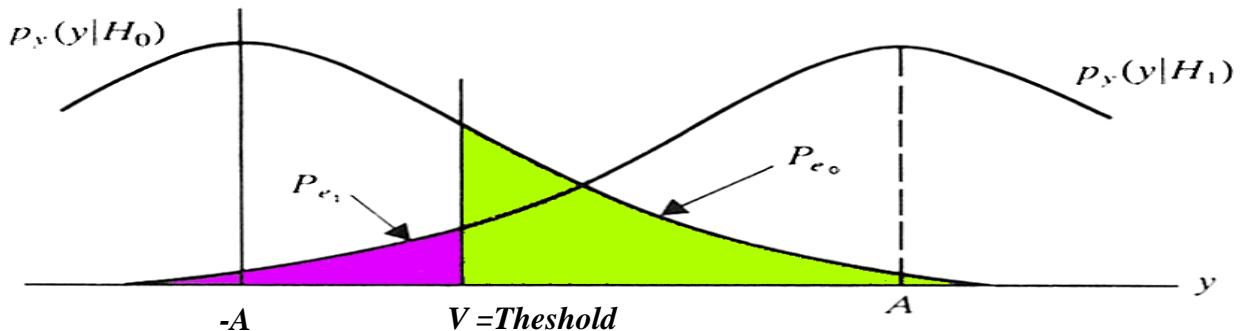
$$p_N(y) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left[-\frac{y^2}{2\sigma^2}\right]$$

Transmitted '0'
but detected as '1'

Error rate and Q-function

$$P_0 = P_1 = 1/2 \Rightarrow P_e = \frac{1}{2}(P_{e0} + P_{e1})$$

V threshold = 0



$$P_{e0} = \int_V^\infty p_N(y) dy$$

$$P_e = P_{e0} = \frac{1}{\sigma\sqrt{2\pi}} \int_{V=0}^\infty \exp\left[-\frac{(y+A)^2}{2\sigma^2}\right] dy$$

This can be expressed by using the Q-function

$$Q(z) \triangleq p(x > z) = \int_z^\infty \frac{1}{\sqrt{2\pi}} e^{-y^2/2} dy.$$

by

$$P_{e0} = \int_V^\infty p_N(y) dy = P_e = Q\left(\frac{A}{\sigma}\right) = Q\left(\sqrt{\frac{A^2}{\sigma^2}}\right)$$

Baseband Binary Error Rate in Terms of Pulse Shape and S/N

setting $V=0$ yields then

$$p_e = \frac{1}{2}(p_{e0} + p_{e1}) = p_{e0} = p_{e1} \Rightarrow p_e = Q\left(\frac{A}{\sigma}\right) = Q\left(\sqrt{\frac{A^2}{\sigma^2}}\right) = Q\left(\sqrt{\frac{S}{N}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

for polar, **rectangular** NRZ [-A,A] bits

Signal power: $S = \frac{1}{2}A^2 + \frac{1}{2}(-A)^2 = A^2$

Probability of occurrence

Noise power: $N = \sigma^2 = \eta \cdot BW_N = N_0 \cdot \frac{R_b}{2} = N_0 \cdot \frac{1}{2T_b}$

Energy Bit to Noise Spectral Density Ratio

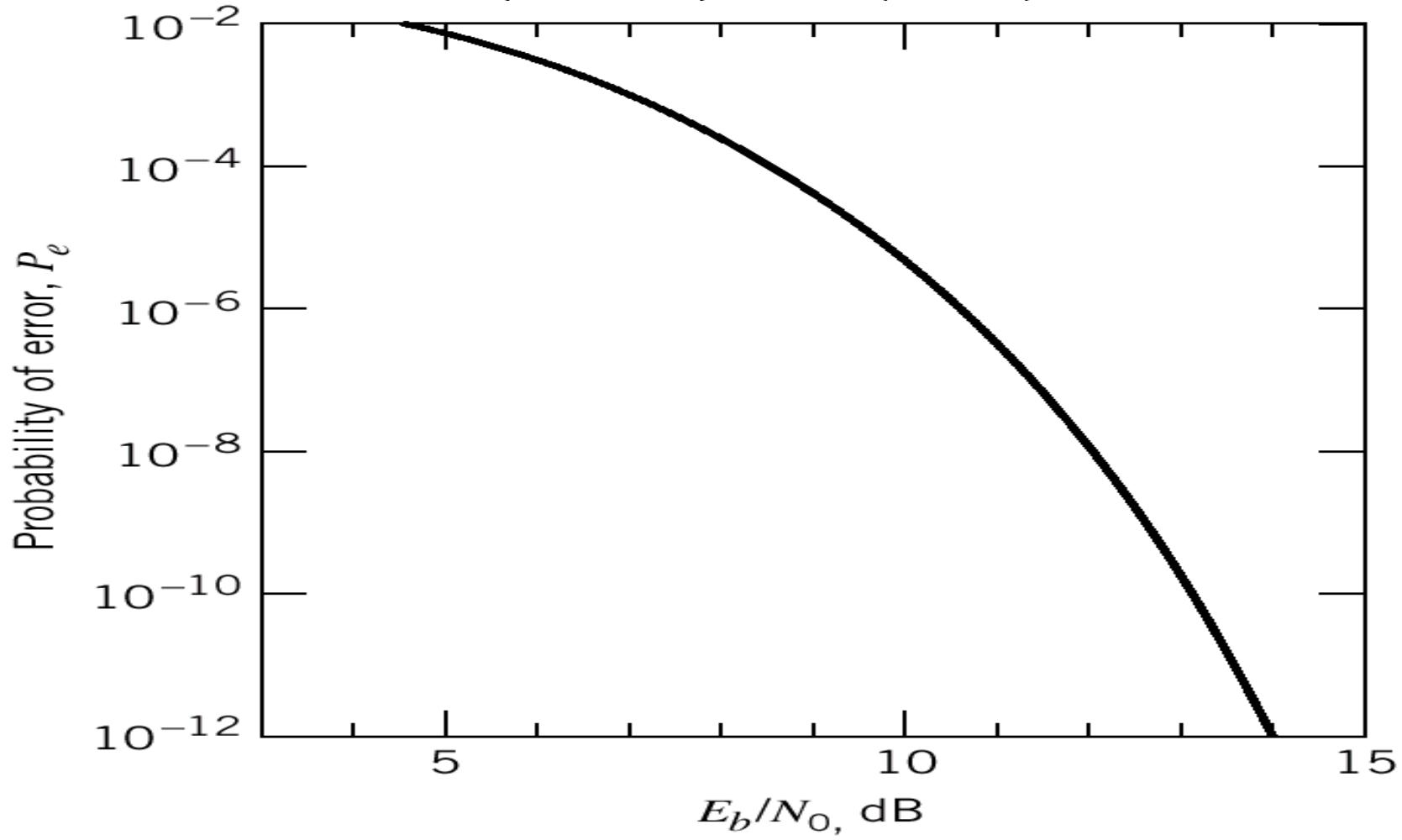
$$\frac{E_b}{N_0} = \frac{S \cdot T_b}{N \cdot BW_N} = \frac{S \cdot T_b}{N \cdot R_b / 2} = \frac{S \cdot T_b}{N} \cdot \frac{R_b}{2} = \frac{S \cdot T_b}{N} \cdot \frac{1}{2 \cdot T_b} = \frac{1}{2} \cdot \frac{S}{N}$$

Note that

$$BW_N = \frac{R_b}{2} \quad (\text{BW pulse shaping filter})$$

When $p_0 = p_1 = 1/2$, the value of V that minimizes the probability of error is $V = 0$.

$$P_e = Q\left(\sqrt{\frac{2E_b}{N_0}}\right) = Q\left(\sqrt{\frac{S}{N}}\right)$$

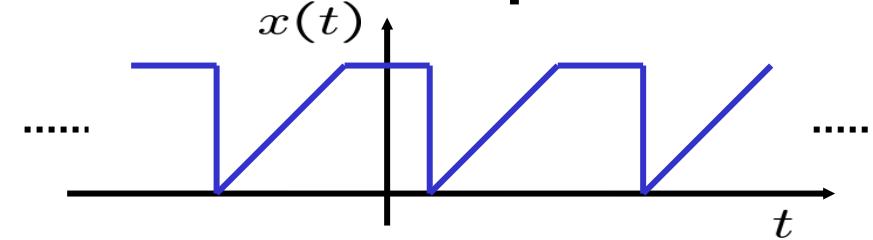


Classification of signals

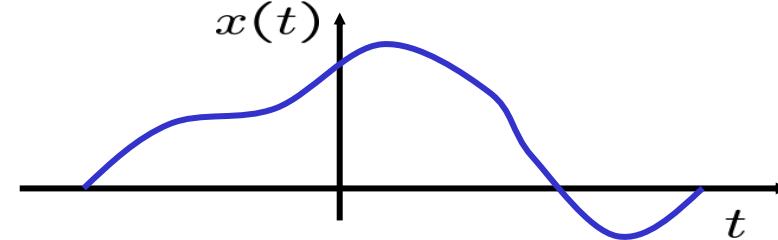
- Deterministic and random signals
 - Deterministic signal: No uncertainty with respect to the signal value at any time.
 - Random signal: Some degree of uncertainty in signal values before it actually occurs.
 - Thermal noise in electronic circuits due to the random movement of electrons
 - Reflection of radio waves from different layers of ionosphere

Classification of signals ...

- Periodic and non-periodic signals

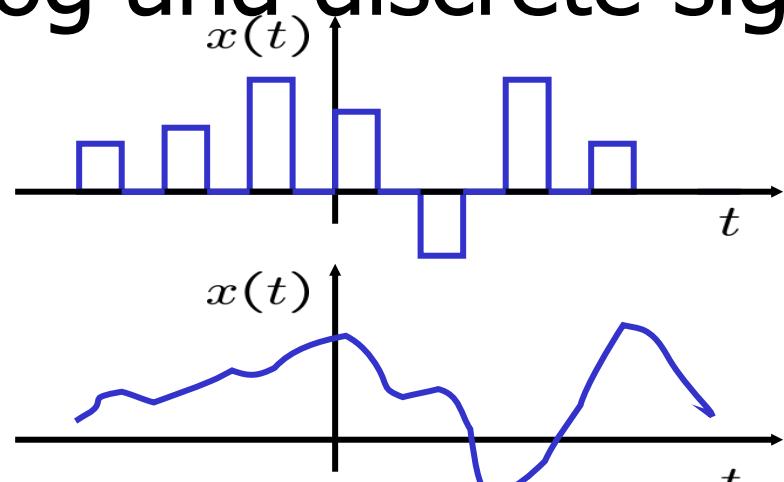


A periodic signal

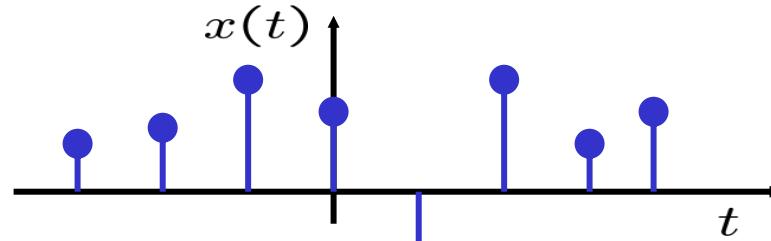


A non-periodic signal

- Analog and discrete signals



Analog signals



A discrete signal

Classification of signals ..

- Energy and power signals

- A signal is an energy signal if, and only if, it has nonzero but finite energy for all time:

$$E_x = \lim_{T \rightarrow \infty} \int_{T/2}^{T/2} |x(t)|^2 dt = \int_{-\infty}^{\infty} |x(t)|^2 dt \quad (0 < E_x < \infty)$$

- A signal is a power signal if, and only if, it has finite but nonzero power for all time:

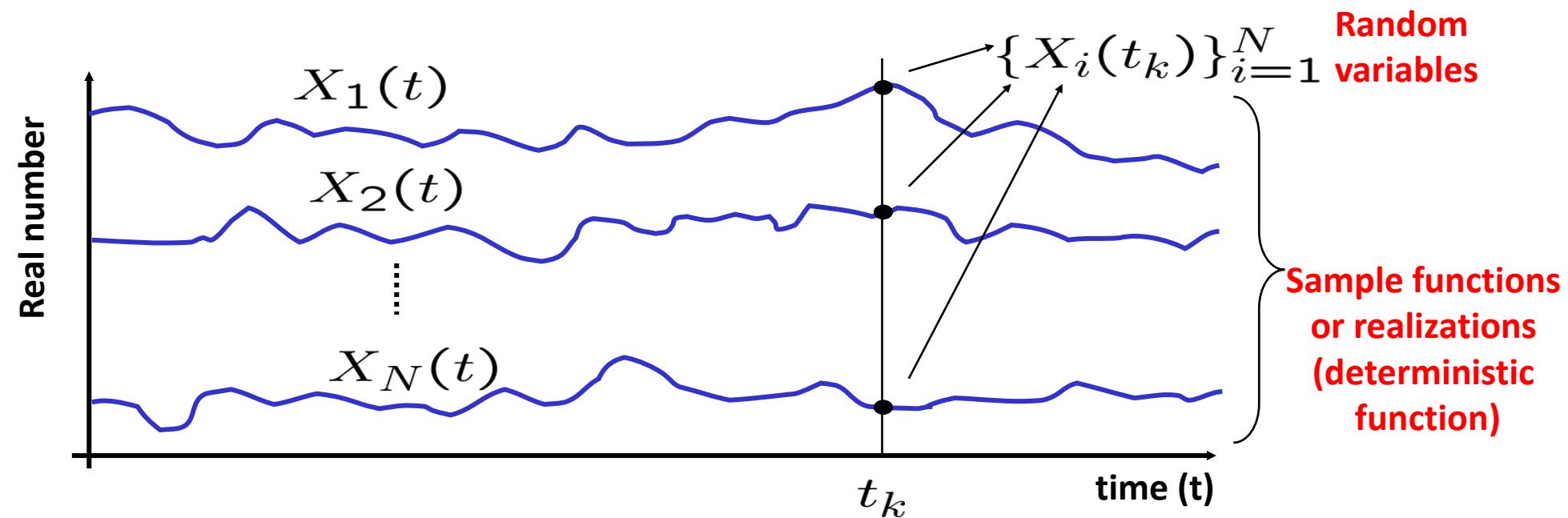
$$(0 < P_x < \infty)$$

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{T/2}^{T/2} |x(t)|^2 dt$$

- General rule: Periodic and random signals are power signals. Signals that are both deterministic and non-periodic are energy signals.

Random process

- A random process is a collection of time functions, or signals, corresponding to various outcomes of a random experiment. For each outcome, there exists a deterministic function, which is called a sample function or a realization.



Random process ...

- Strictly stationary: If none of the statistics of the random process are affected by a shift in the time origin.
- Wide sense stationary (WSS): If the mean and autocorrelation function do not change with a shift in the origin time.
- Cyclostationary: If the mean and autocorrelation function are periodic in time.
- Ergodic process: A random process is ergodic in mean and autocorrelation, if

and

$$m_X = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} X(t) dt$$

, respectively.

$$R_X(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} X(t) X^*(t - \tau) dt$$

Autocorrelation

- Autocorrelation of an energy signal

$$R_x(\tau) = x(\tau) \star x^*(-\tau) = \int_{-\infty}^{\infty} x(t)x^*(t - \tau)dt$$

- Autocorrelation of a power signal

$$R_x(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t)x^*(t - \tau)dt$$

- For a periodic signal:

$$R_x(\tau) = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} x(t)x^*(t - \tau)dt$$

- Autocorrelation of a random signal

$$R_X(t_i, t_j) = \mathbb{E}[X(t_i)X^*(t_j)]$$

- For a WSS process:

$$R_X(\tau) = \mathbb{E}[X(t)X^*(t - \tau)]$$

Spectral density

- Energy signals:

$$E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} |X(f)|^2 df$$

- Energy spectral density (ESD):

$$\Psi_x(f) = |X(f)|^2$$

- Power signals:

$$P_x = \frac{1}{T_0} \int_{T_0/2}^{T_0/2} |x(t)|^2 dt = \sum_{n=-\infty}^{\infty} |c_n|^2 \quad \{c_n\} = \mathcal{F}[x(t)]$$

- Power spectral density (PSD):

$$G_x(f) = \sum_{n=-\infty}^{\infty} |c_n|^2 \delta(f - n f_0) \quad f_0 = 1/T_0$$

- Random process:

- Power spectral density (PSD):

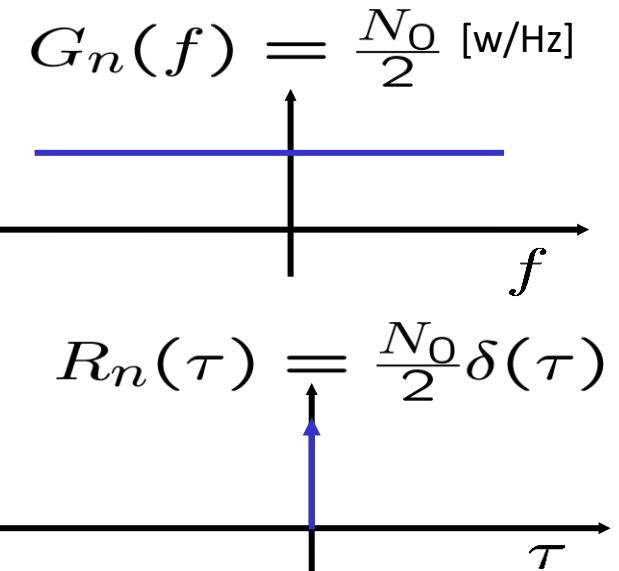
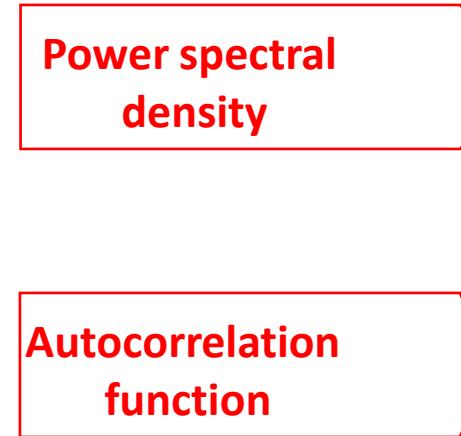
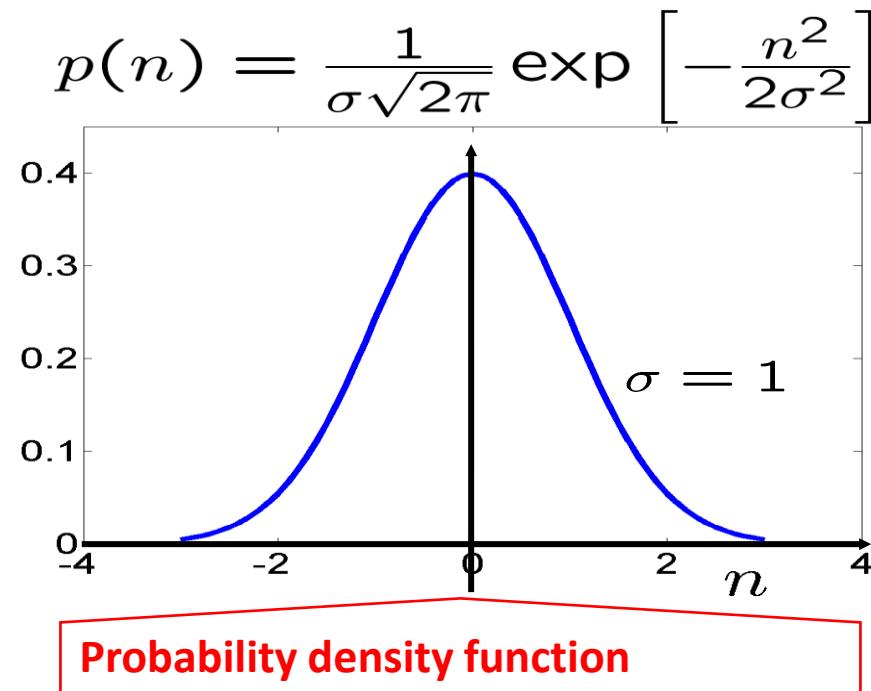
$$G_X(f) = \mathcal{F}[R_X(\tau)]$$

Properties of an autocorrelation function

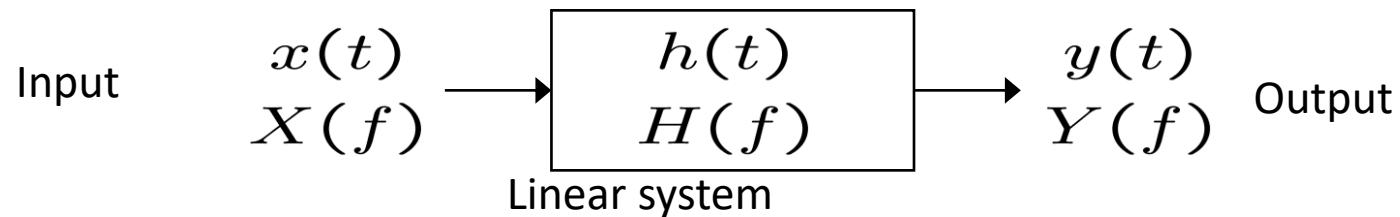
- For real-valued (and WSS in case of random signals):
 1. Autocorrelation and spectral density form a Fourier transform pair.
 2. Autocorrelation is symmetric around zero.
 3. Its maximum value occurs at the origin.
 4. Its value at the origin is equal to the average power or energy.

Noise in communication systems

- Thermal noise is described by a zero-mean Gaussian random process, $n(t)$.
- Its PSD is flat, hence, it is called white noise.



Signal transmission through linear systems



- Deterministic signals:
- Random signals:
- Ideal distortionless transmission:
All the frequency components of the signal not only arrive with an identical time delay, but also are amplified or attenuated equally.

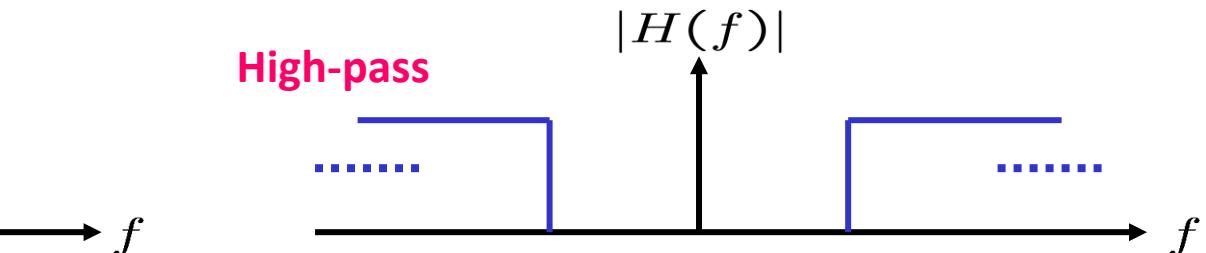
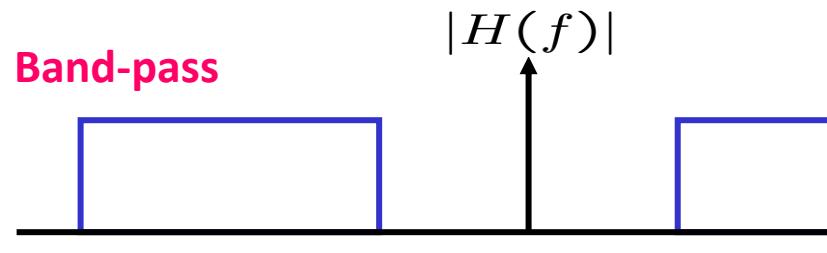
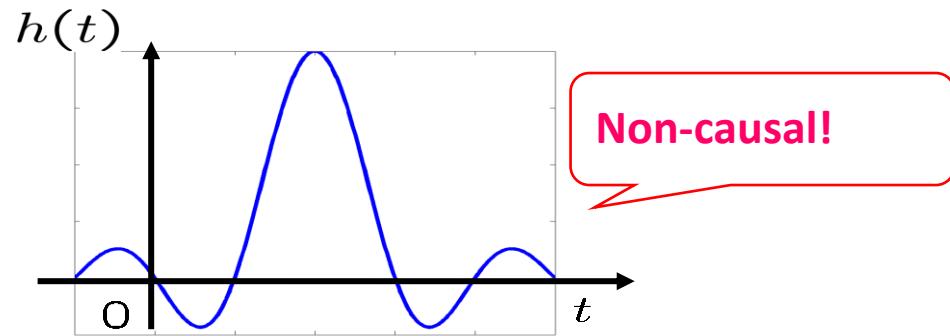
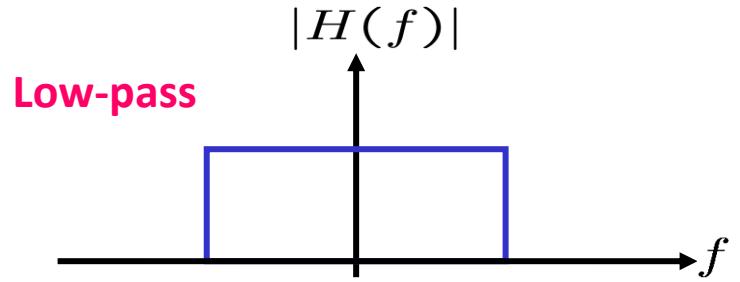
$$Y(f) = X(f)H(f)$$

$$G_Y(f) = G_X(f)|H(f)|^2$$

$$y(t) = Kx(t - t_0) \text{ or } H(f) = Ke^{-j2\pi f t_0}$$

Signal transmission ... - cont'd

- Ideal filters:



- Realizable filters:

RC filters

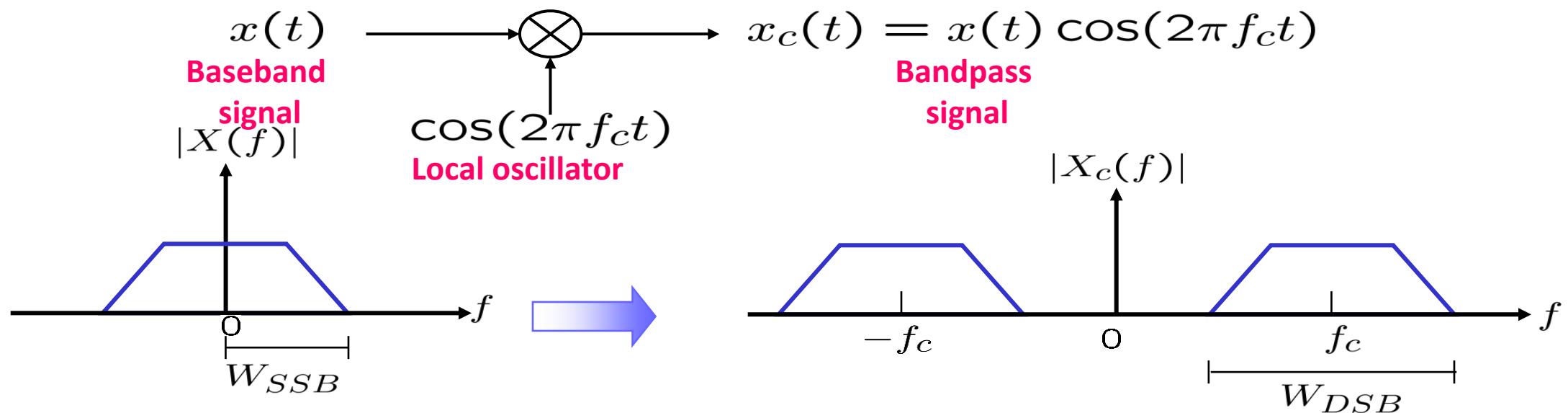
Butterworth filter

$$H(f) = \frac{1}{1+j2\pi fRC}$$

$$|H_n(f)| = \frac{1}{\sqrt{1+(f/f_u)^{2n}}}$$

Bandwidth of signal

- Baseband versus bandpass:

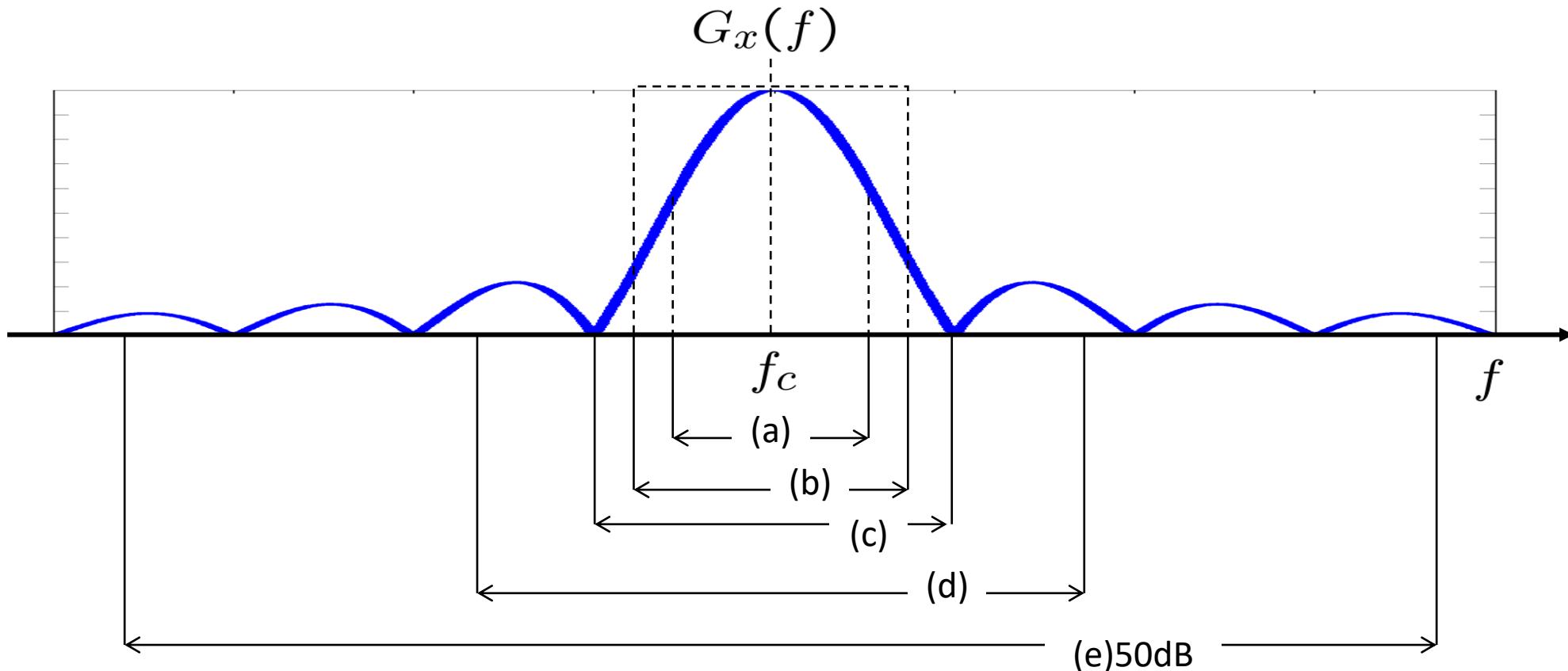


- Bandwidth dilemma:
 - Bandlimited signals are not realizable!
 - Realizable signals have infinite bandwidth!

Bandwidth of signal – cont'd

- Different definition of bandwidth:

- a) Half-power bandwidth
- b) Noise equivalent bandwidth
- c) Null-to-null bandwidth
- d) Fractional power containment bandwidth
- e) Bounded power spectral density
- f) Absolute bandwidth



End of Module 10
